

Fully-Implicit Techniques for Ocean Circulation Problems

Wilbert Weijer

Los Alamos National Laboratory

CCS-2

wilbert@lanl.gov

Collaborator:

Henk Dijkstra (Utrecht University)

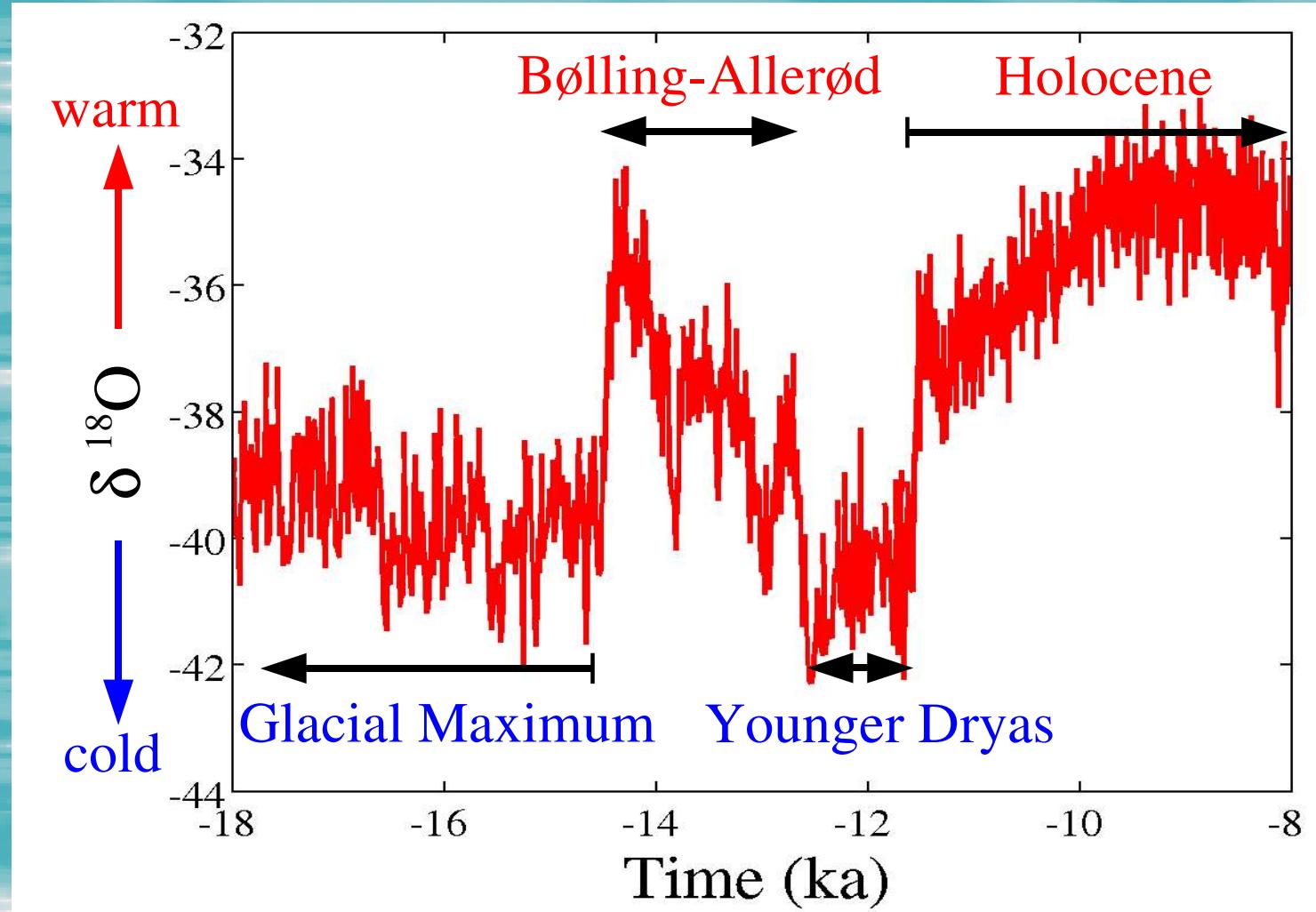
Overview

Studies of the Meridional Overturning Circulation

- Multiple Equilibria
 - Parameter continuation
- Oscillatory Modes
 - Linear stability analysis
- Optimal Perturbations
 - Generalized Stability Analysis

Abrupt Climate Change

Younger Dryas in Greenland ice core



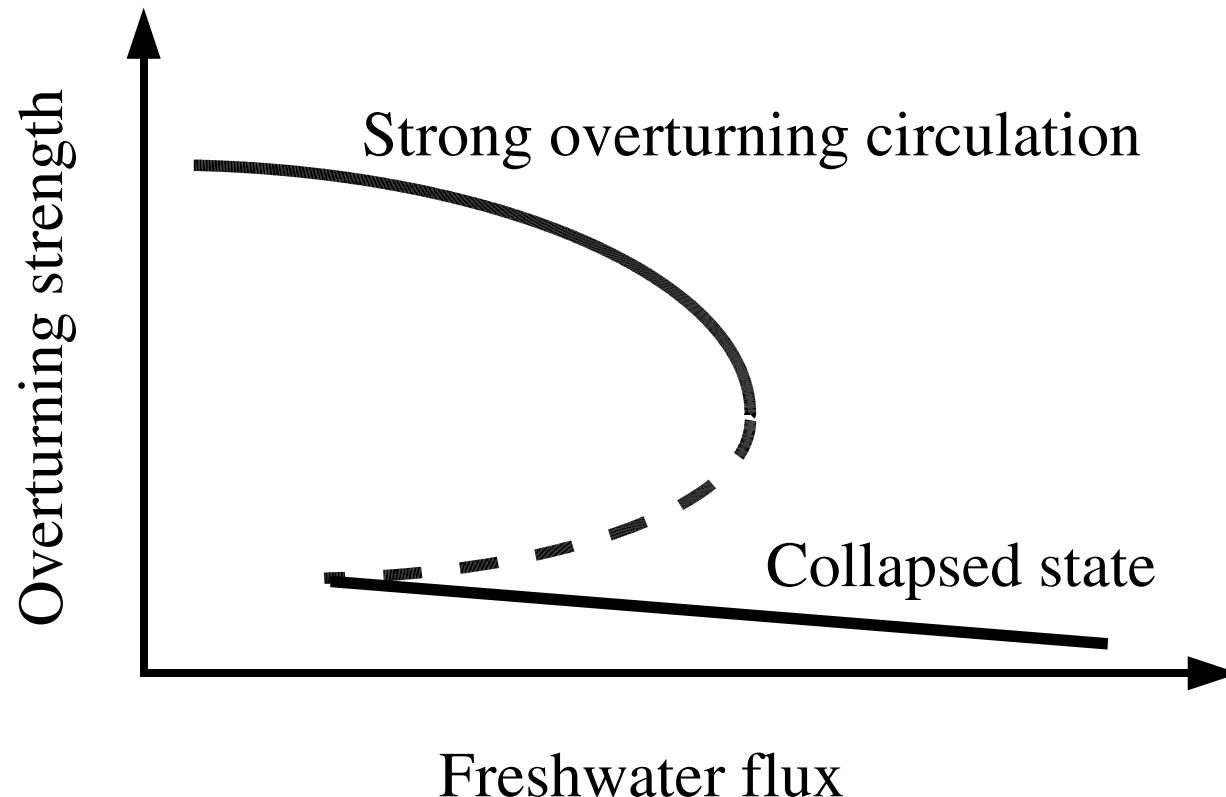
Abrupt Climate Change

Regime switches of the overturning circulation

- Leading hypothesis:
 - Transition between *multiple equilibria* of the overturning circulation

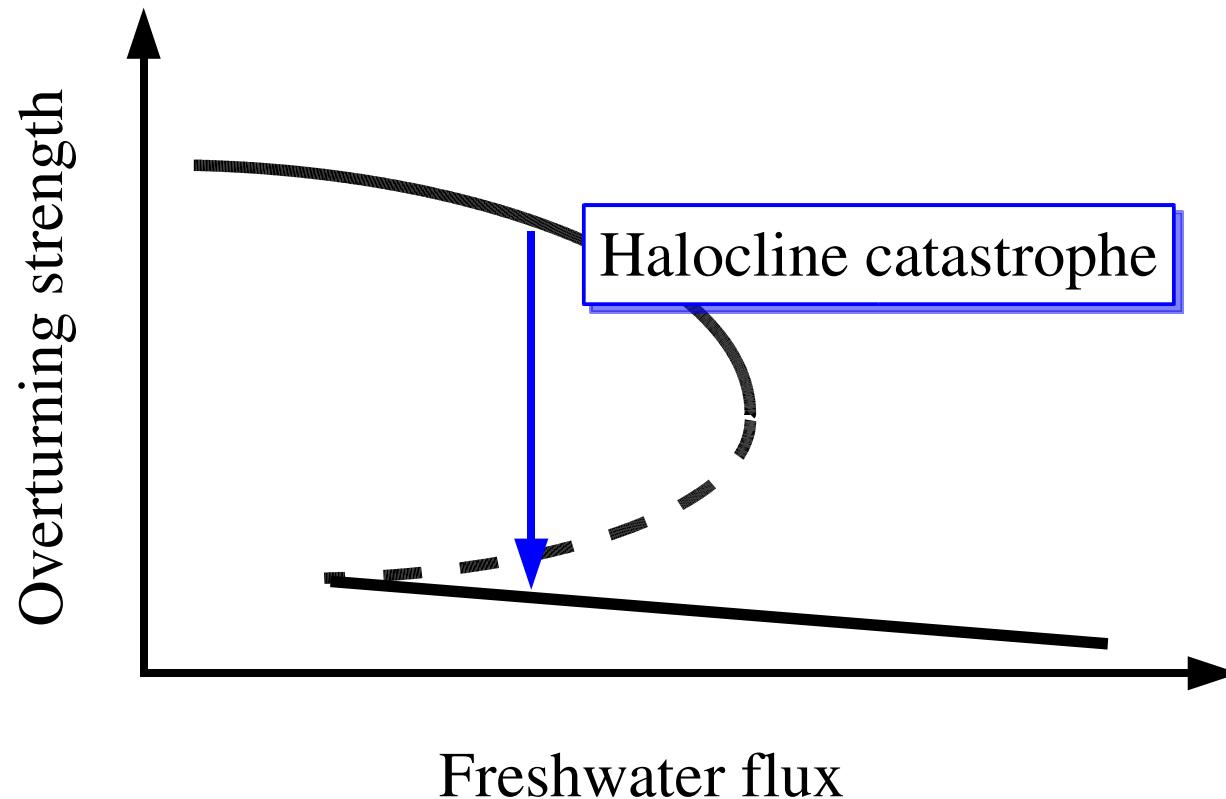
Abrupt Climate Change

Regime switches of the overturning circulation



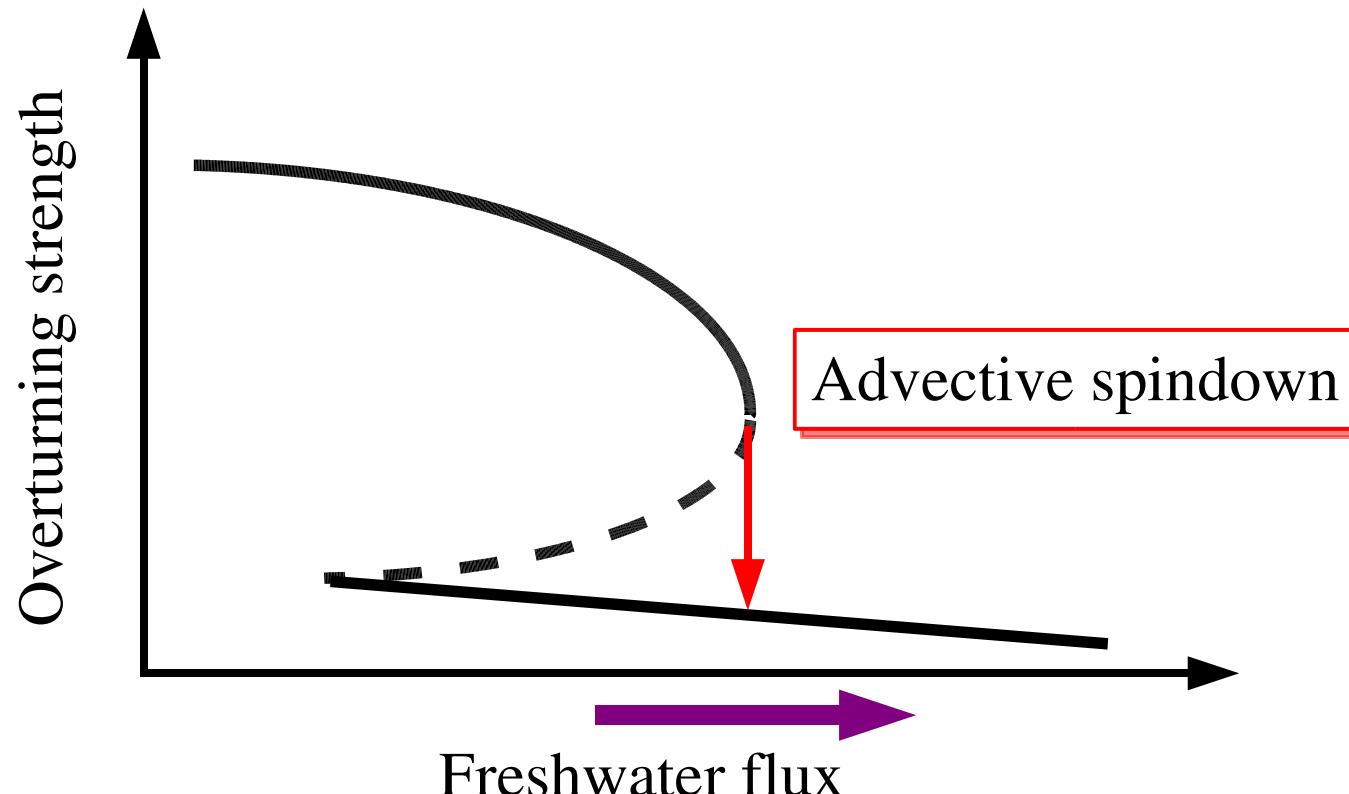
Abrupt Climate Change

Regime switches of the overturning circulation



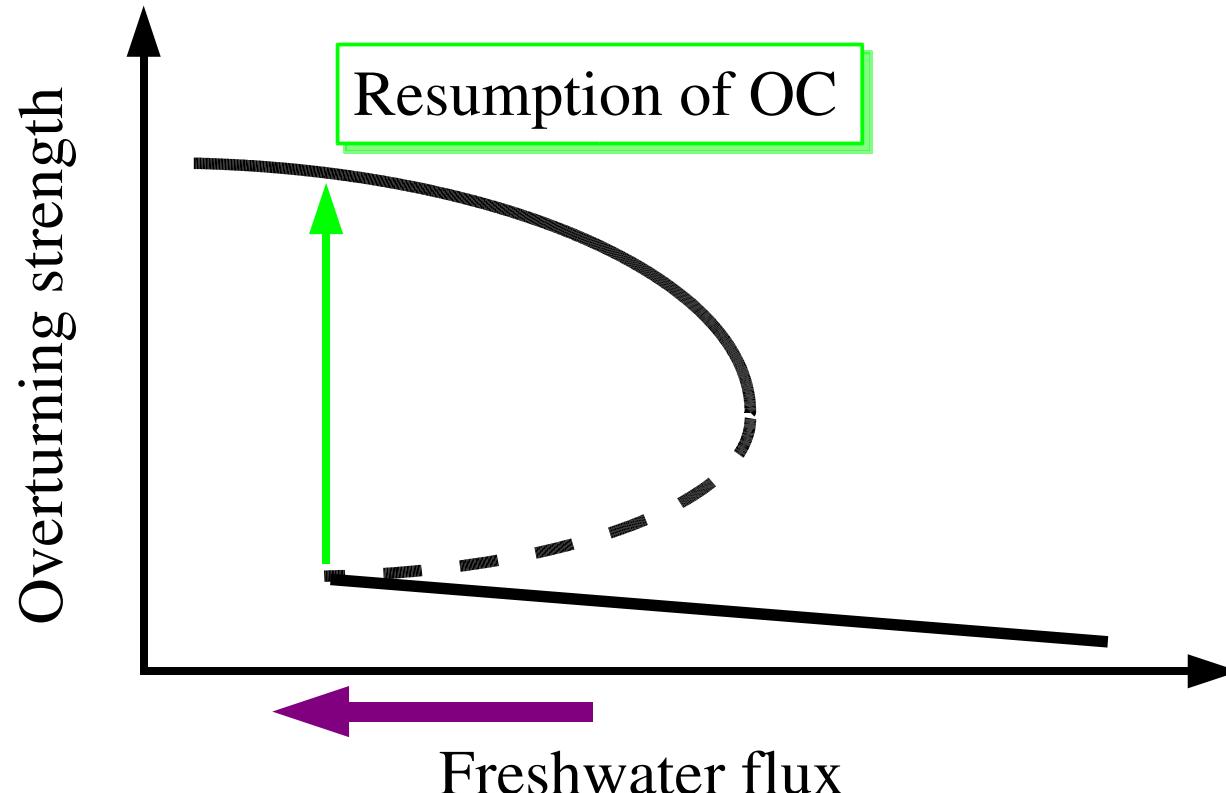
Abrupt Climate Change

Regime switches of the overturning circulation



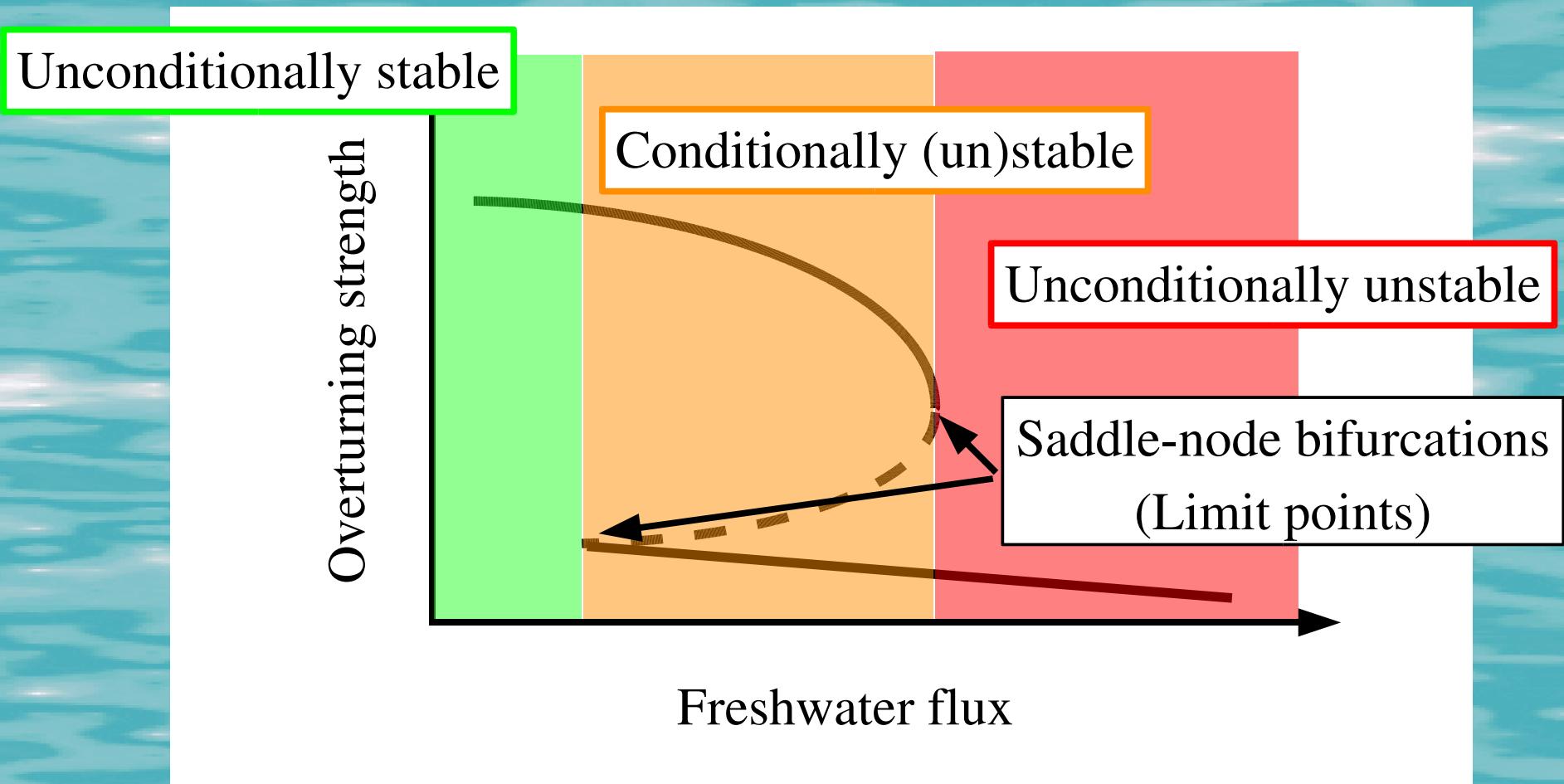
Abrupt Climate Change

Regime switches of the overturning circulation



Abrupt Climate Change

Regime switches of the overturning circulation



Abrupt Climate Change

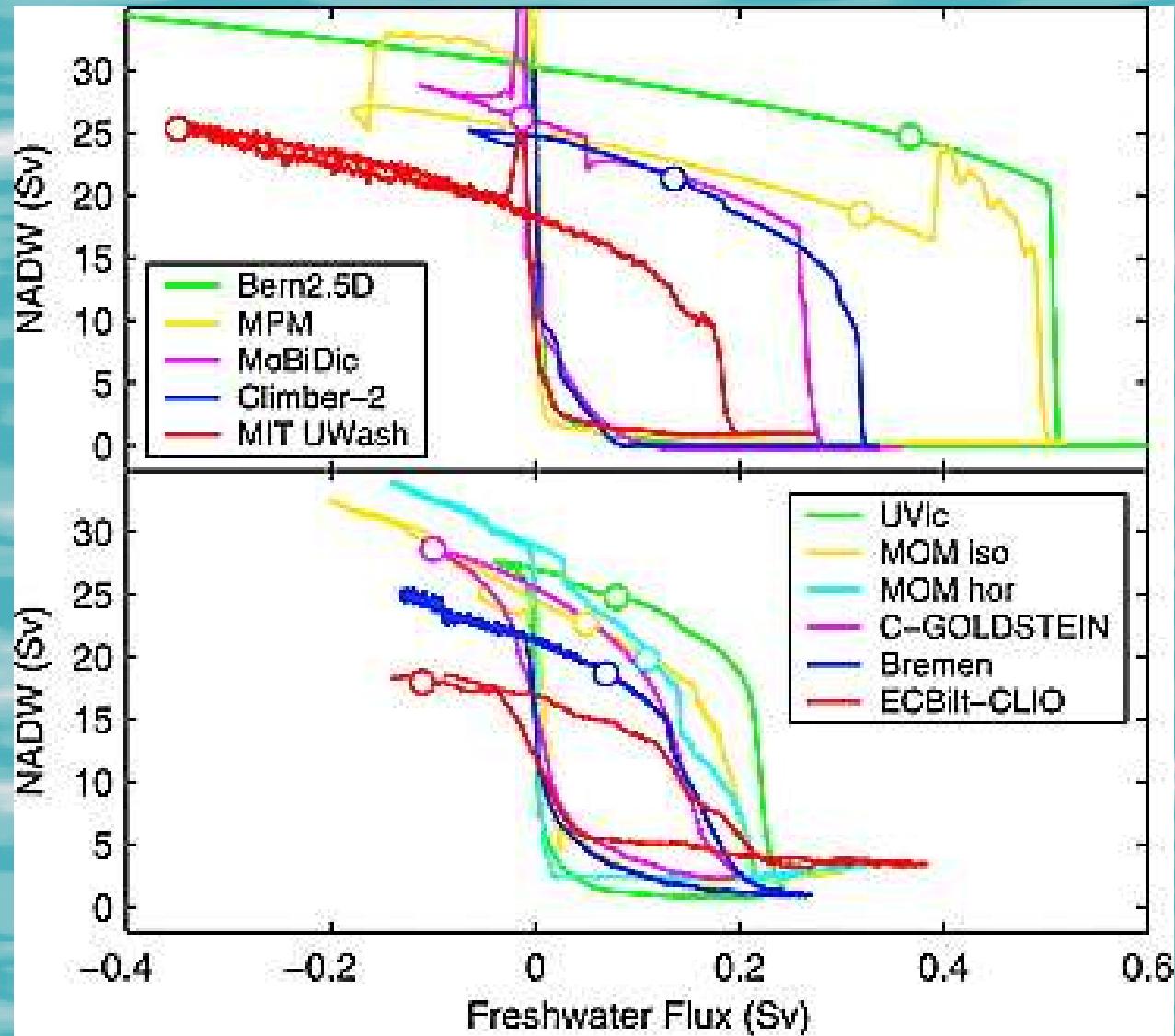
Hosing Experiments

- Traditionally studied with *hosing experiments*:
 - Slowly increase freshwater input in North Atlantic
 - Follow quasi-steady ocean circulation

Abrupt Climate Change

Hosing Experiments

2D models

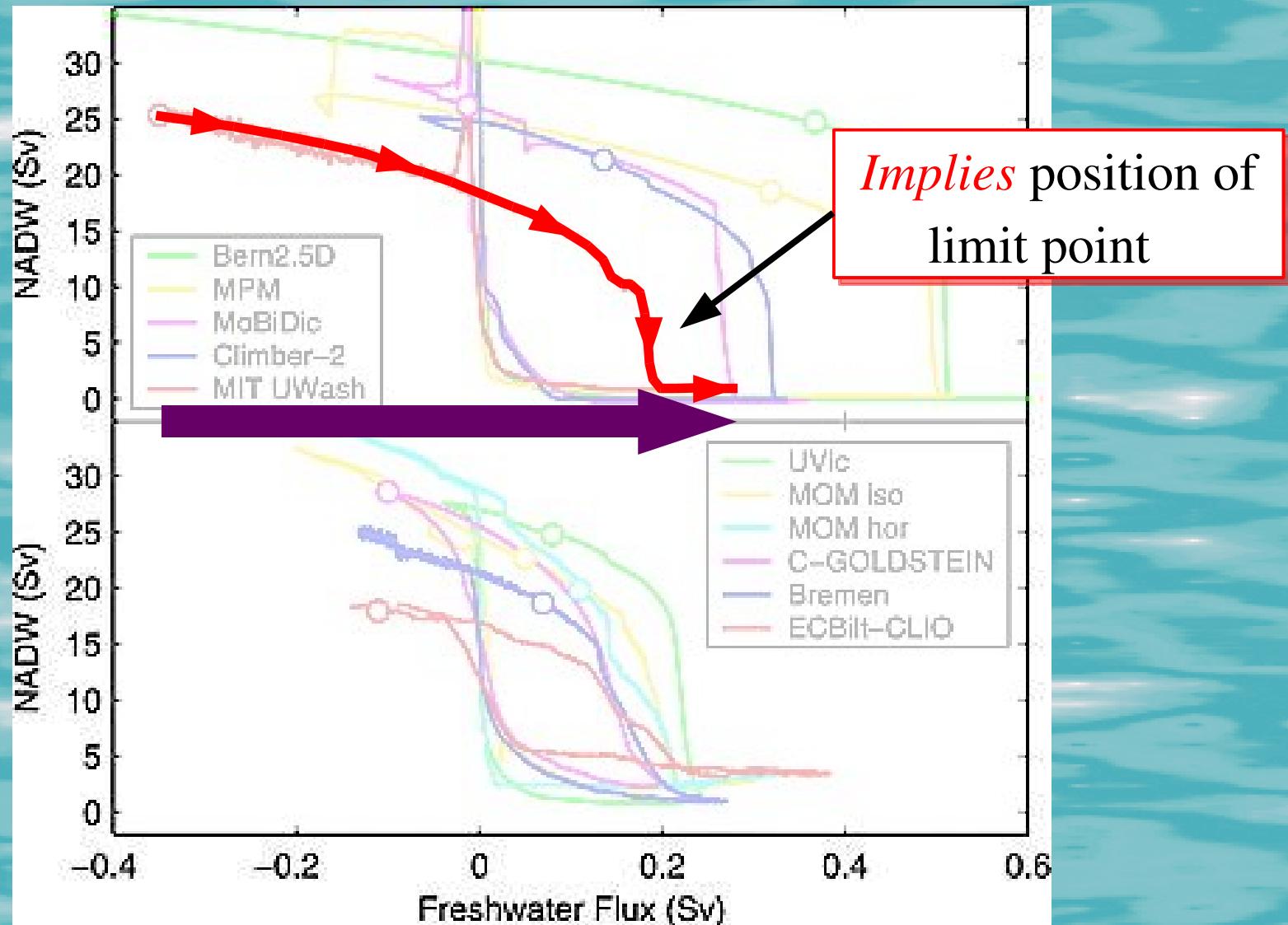


3D models

Abrupt Climate Change

Hosing Experiments

2D models



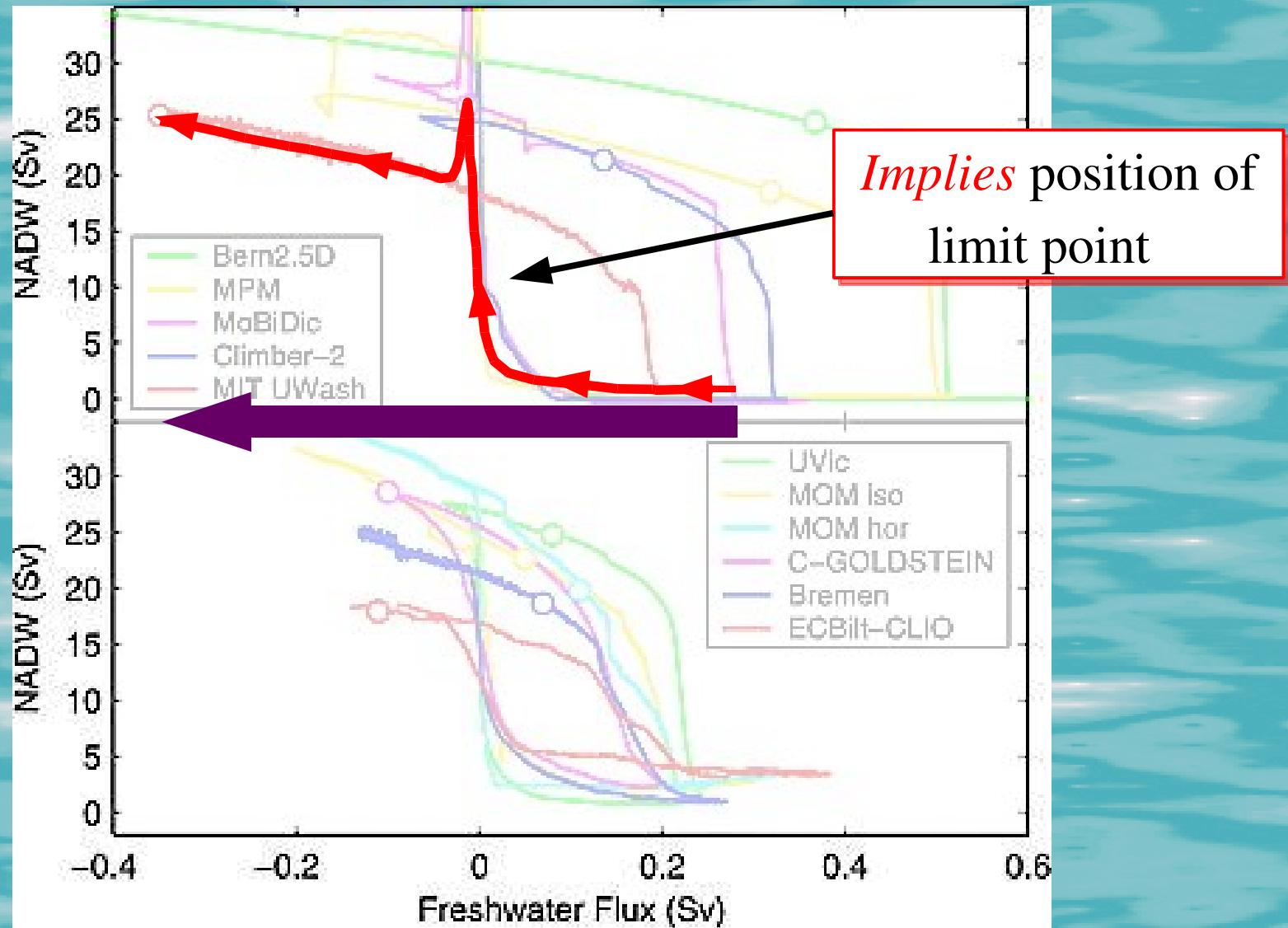
3D models

Implies position of
limit point

Abrupt Climate Change

Hosing Experiments

2D models

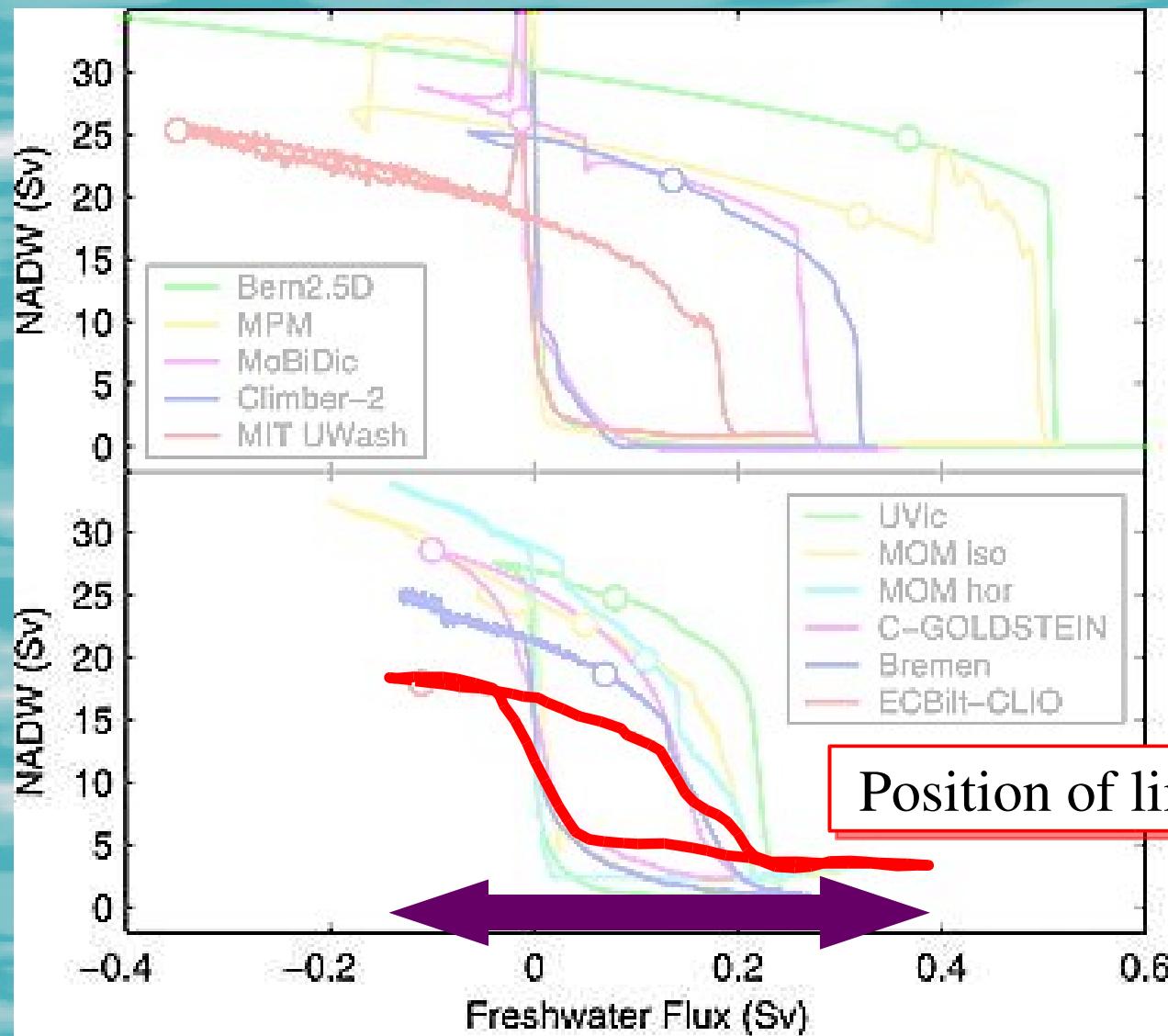


3D models

Abrupt Climate Change

Hosing Experiments

2D models



3D models

Position of limit points?

Abrupt Climate Change

Hosing Experiments

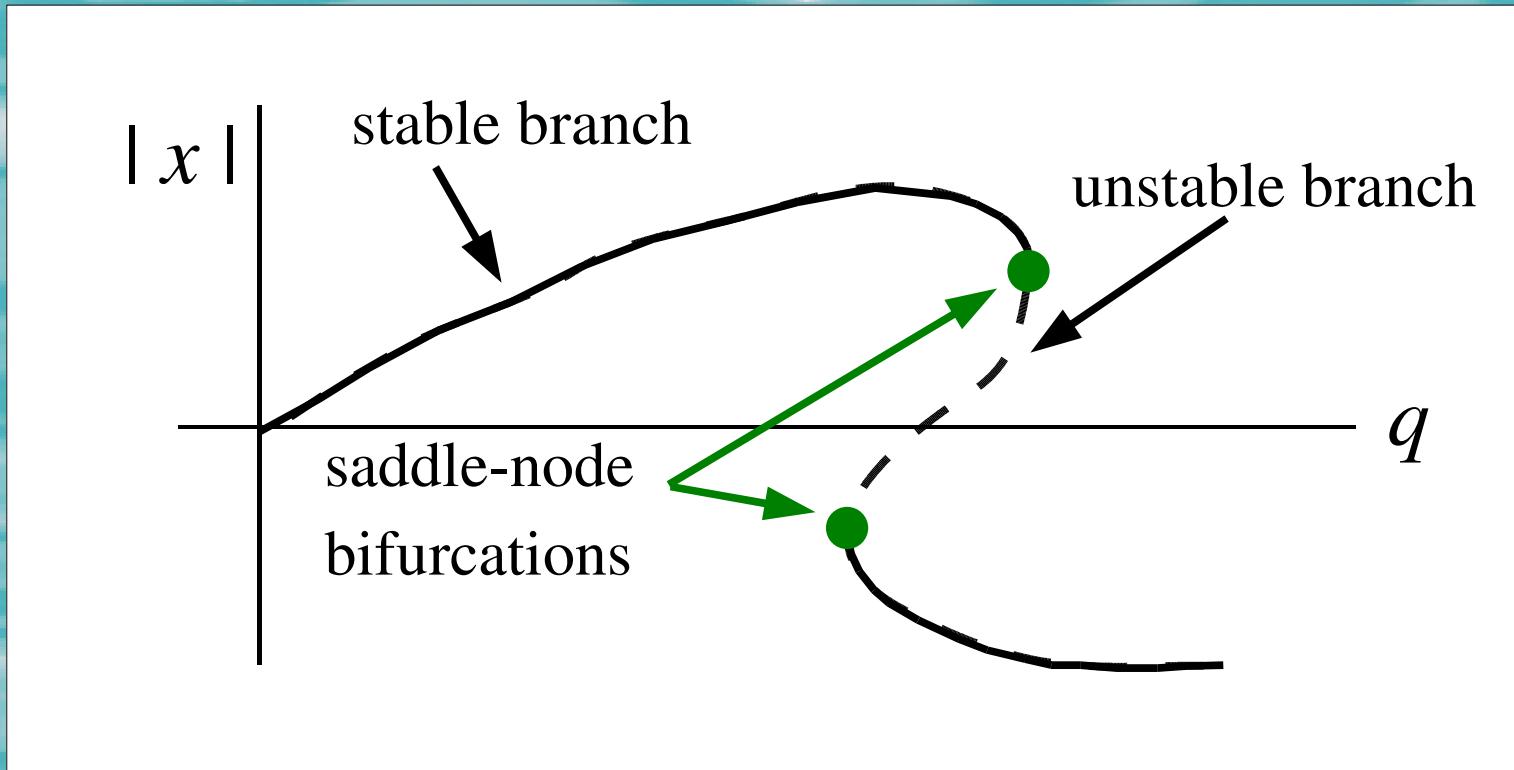
- ➊ Drawbacks:
 - Inaccurate due to transient response of MOC
 - Inefficient due to long time integrations
 - No info about unstable steady state connecting stable branches

Abrupt Climate Change

Parameter Continuation

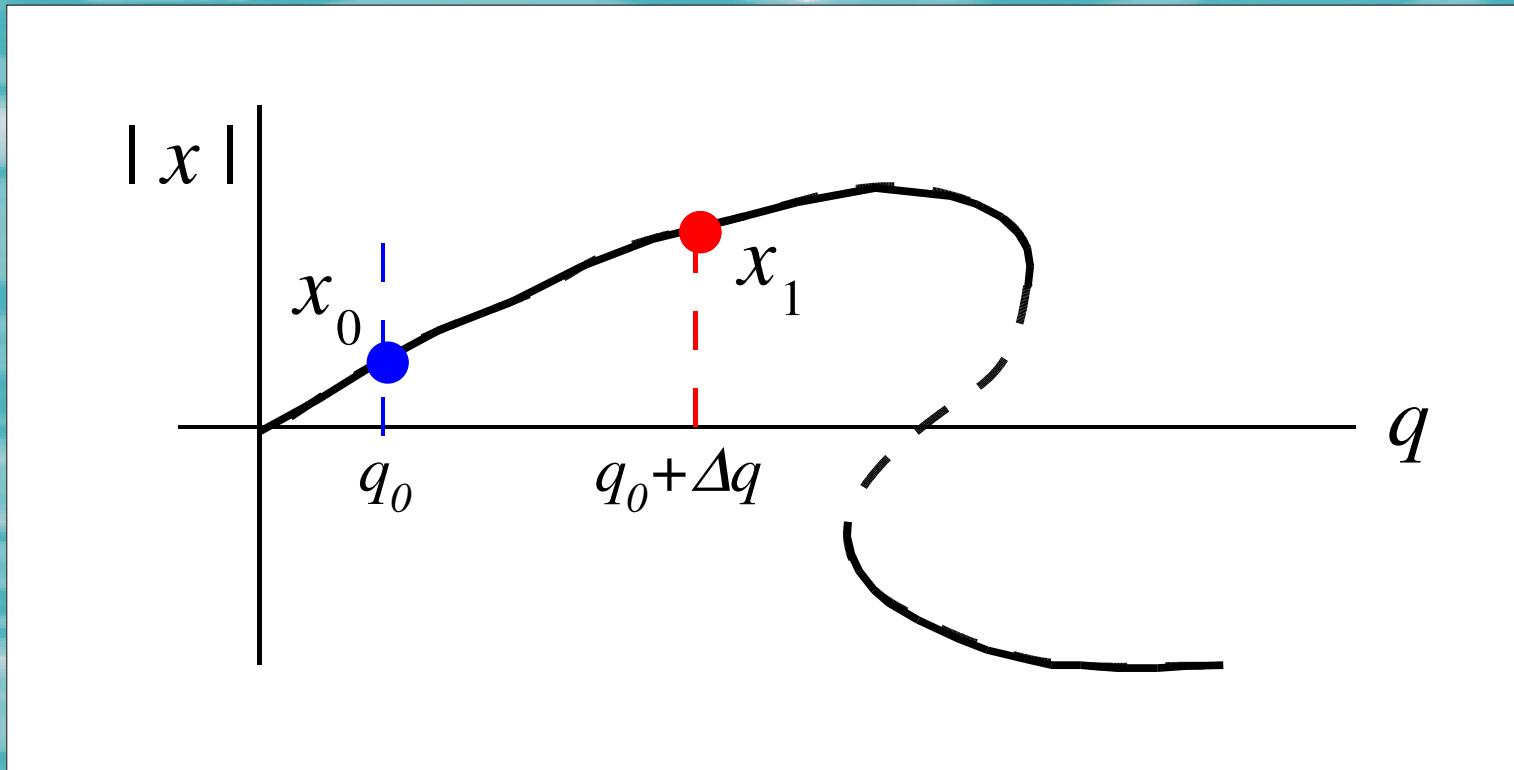
- Drawbacks:
 - Inaccurate due to transient response of MOC
 - Inefficient due to long time integrations
 - No info about unstable steady state connecting stable branches
- Alternative: *parameter continuation*
 - Calculate **branches of steady states** as function of parameter

Parameter Continuation



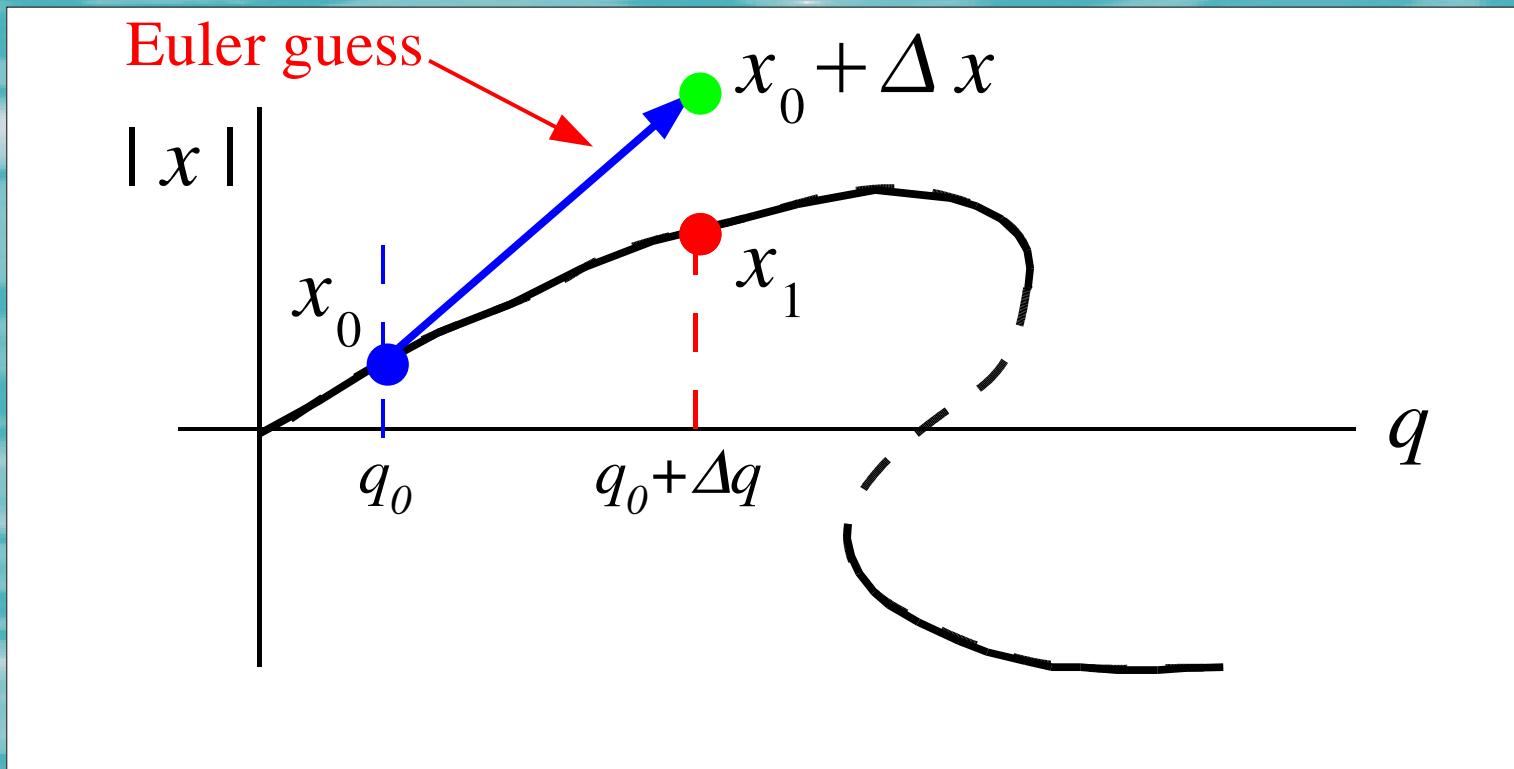
$$\frac{dx}{dt} = \Phi(x, q) = 0$$

Parameter Continuation



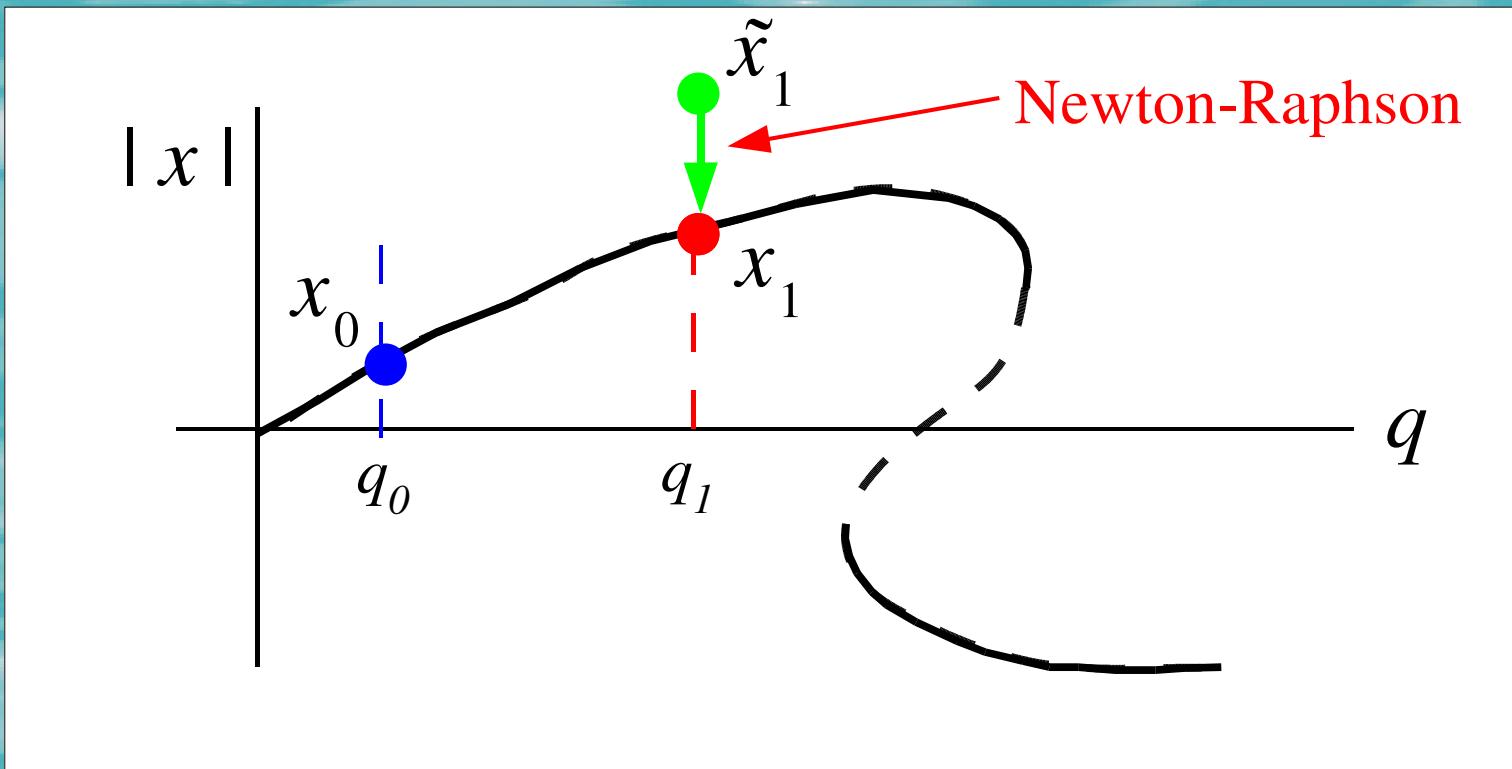
$$\frac{dx}{dt} = \Phi(x, q) = 0$$

Parameter Continuation



$$\Delta x = -(\Phi_x)^{-1} \Phi_q \Delta q$$

Parameter Continuation



$$\Delta x = -(\Phi_x)^{-1} \Phi(\tilde{x}_1, q_1)$$

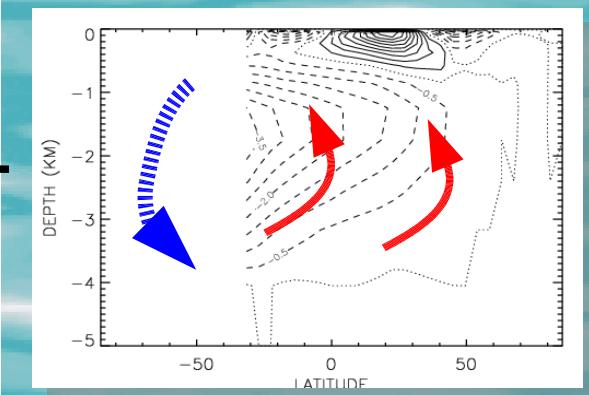
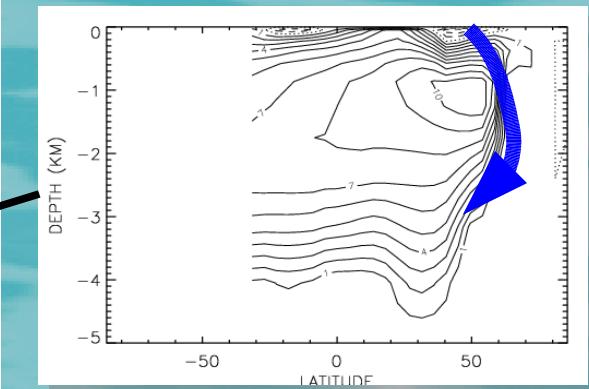
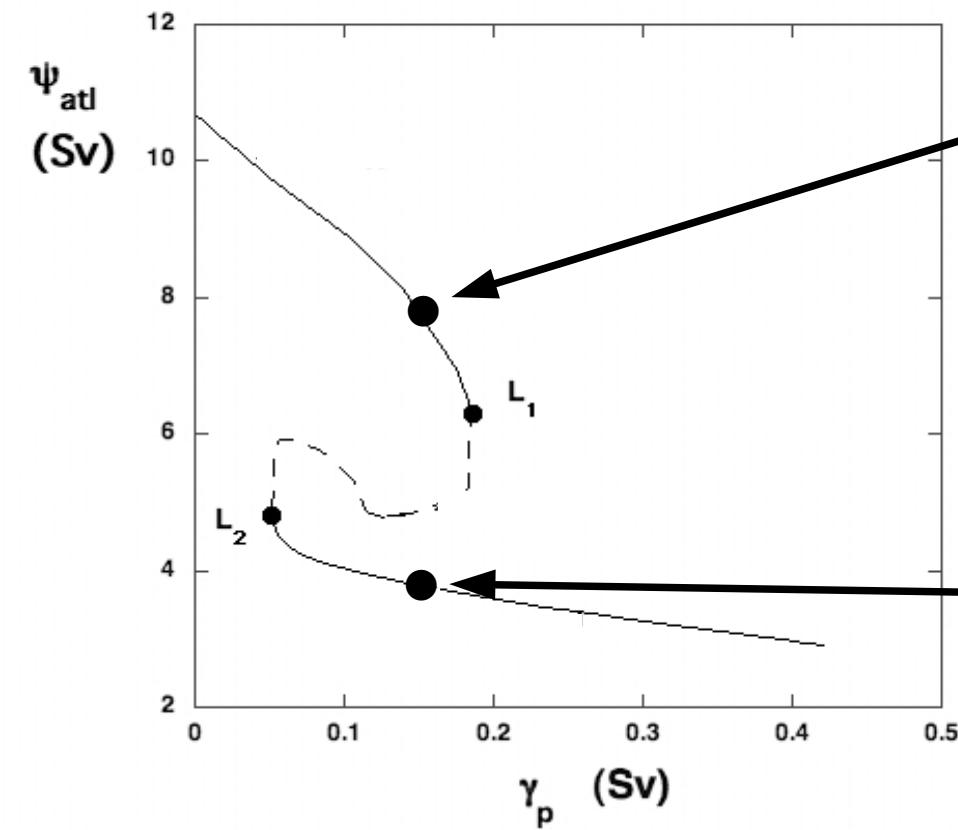
Parameter Continuation

- Fully implicit ocean model: THCM (*Weijer et al., 2003*)
 - Jacobian explicitly constructed
- Algebraic system solvers:
 - GMRES: iterative linear systems solver (*Saad & Schultz, 1986*)
 - MRILU: preconditioner (*Botta & Wubs, 1999*)

Parameter Continuation

- Global configuration
 - Realistic bathymetry
 - 4° resolution, 12 levels
- Variational Parameter
 - γ_p : North Atlantic freshwater flux perturbation

Parameter Continuation



Climate Variability

Linear Stability Analysis

- What are the “most dangerous” perturbations?
- Traditional approach: **Linear Stability Analysis**
 - Determine least stable normal modes
 - Stationary/Oscillatory
 - Spatial patterns, growth/decay rate, frequency

Eigenvalue Analysis

Steady state:

$$M \frac{d\bar{x}}{dt} = \Phi(\bar{x}) = 0$$

Eigenvalue Analysis

Steady state:

$$M \frac{d\bar{x}}{dt} = \Phi(\bar{x}) = 0$$

$$M \frac{dx'}{dt} = J(\bar{x})x'$$

$$x = \bar{x} + x'$$

Eigenvalue Analysis

Steady state:

$$M \frac{d \bar{x}}{dt} = \Phi(\bar{x}) = 0$$

$$M \frac{d x'}{dt} = J(\bar{x}) x'$$

$$\sigma M x'_0 = J(\bar{x}) x'_0$$

$$x = \bar{x} + x'$$

$$x' = x'_0 \exp(\sigma t)$$

Eigenvalue Analysis

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$$x = \bar{x} + x'$$

$$x' = x'_0 \exp(\sigma t)$$

$$\sigma A x = B x$$

Generalized eigenproblem

Eigenvalue Analysis

- ➊ Eigenvalue solvers:

- Jacobi-Davidson QZ-method: modes closest to “target”

(Sleijpen & Van der Vorst, 1996)

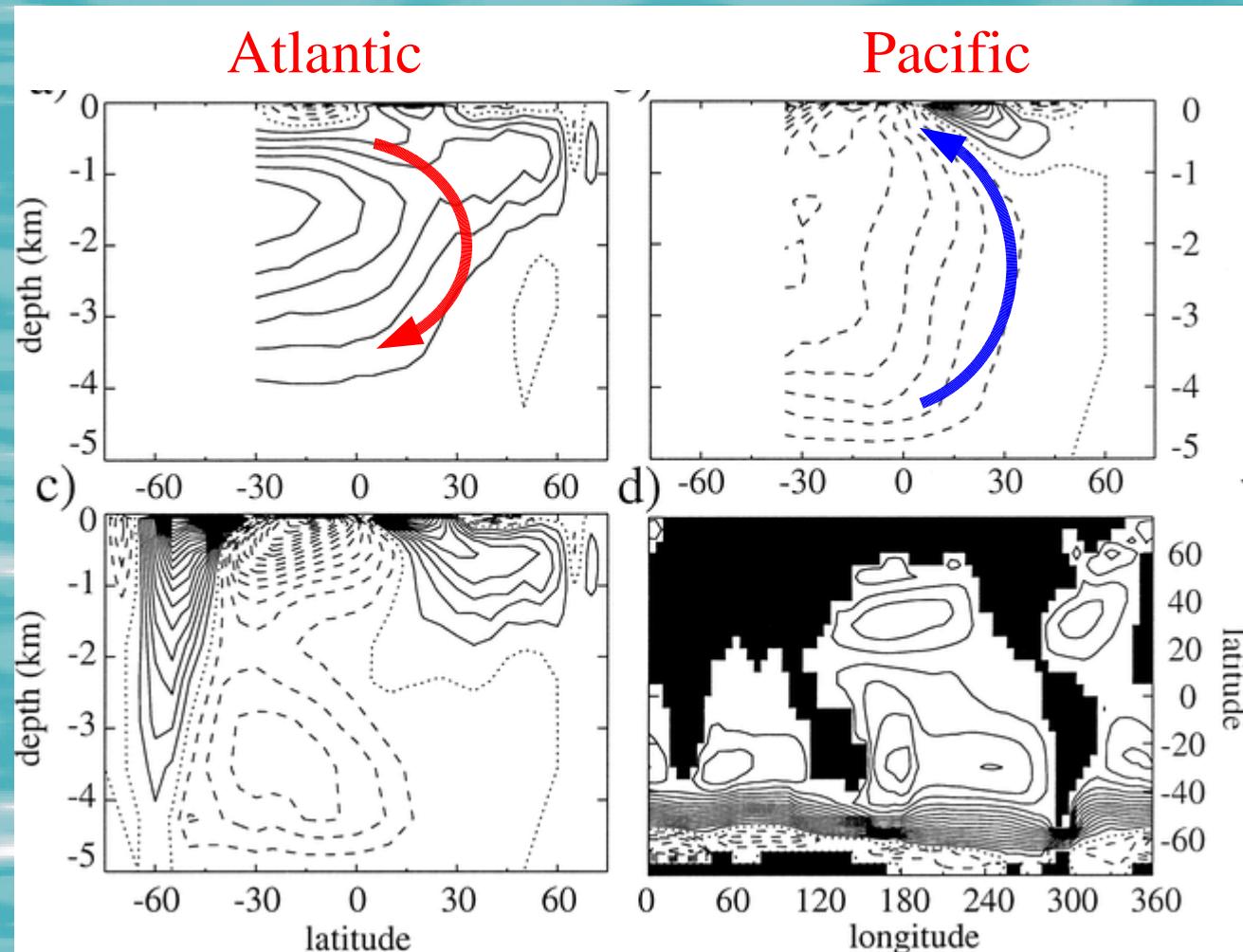
- Simultaneous Iteration Technique: most “dangerous” modes

(Steward & Jennings, 1981)

Climate Variability

Linear Stability Analysis

Basic State

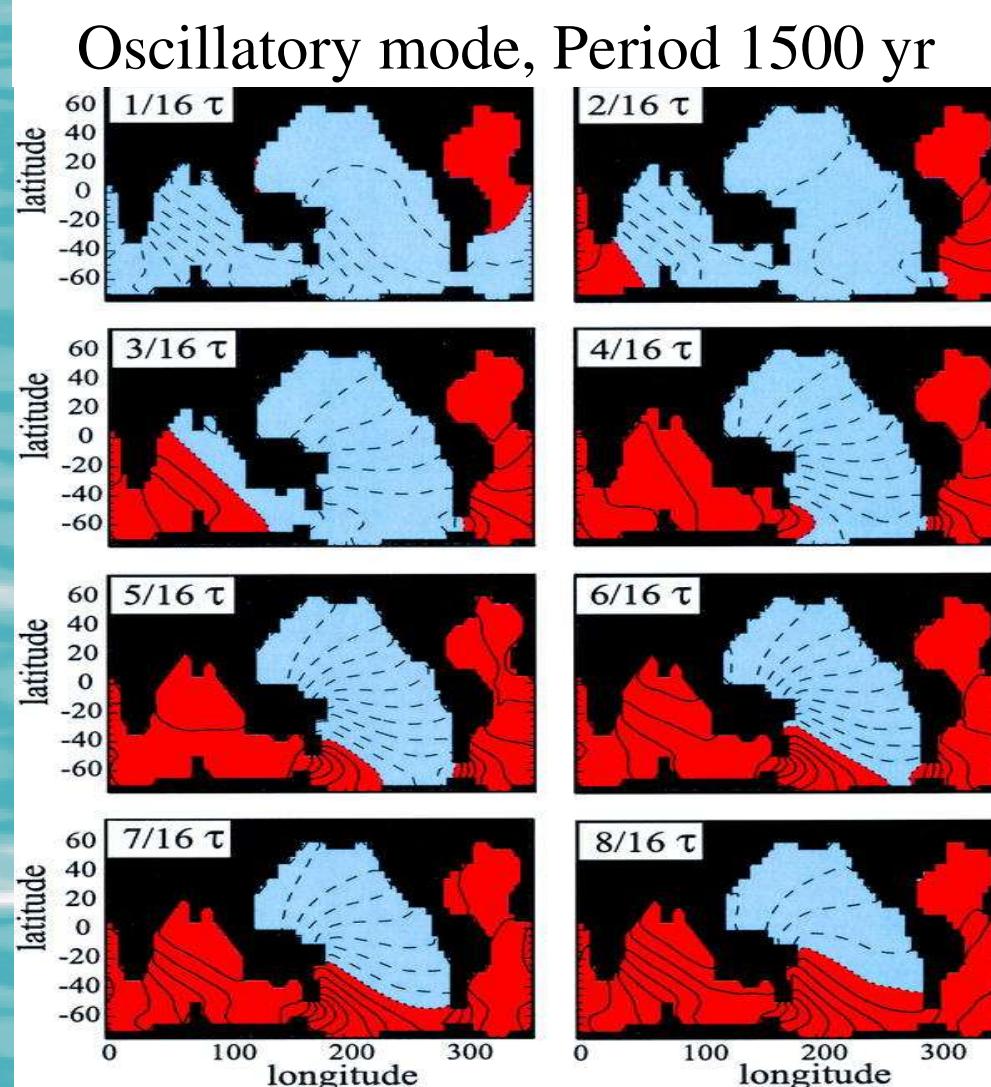


(Weijer and Dijkstra, 2003)

Climate Variability

Linear Stability Analysis

T-anomaly at
300 m depth



(Weijer and Dijkstra, 2003)

Climate Variability

Generalized Stability Analysis

- What are the “most dangerous” perturbations?
- Traditional approach: **Linear Stability Analysis**
 - Determine least stable normal modes
 - Stationary/Oscillatory
 - Spatial patterns, growth/decay rate, frequency
- Alternative approach: **Generalized Stability Analysis**
 - Determine perturbations that lead to optimal (initial) growth
 - Uses adjoint of tangent linear model

Generalized Stability Analysis

Steady state:

$$M \frac{d \bar{x}}{dt} = \Phi(\bar{x}) = 0$$

$$M \frac{d x'}{dt} = A x'$$

$$x = \bar{x} + x'$$

Generalized Stability Analysis

Steady state:

$$M \frac{d \bar{x}}{dt} = \Phi(\bar{x}) = 0$$

$$M \frac{d x'}{dt} = A x'$$

$$x = \bar{x} + x'$$

$$x'(t_{n+1}) = x'(t_n) P(t_{n+1}; t_n)$$

$$P(t_{n+1}; t_n) = \exp(M^{-1} A \Delta t)$$

Generalized Stability Analysis

Steady state:

$$M \frac{d \bar{x}}{dt} = \Phi(\bar{x}) = 0$$

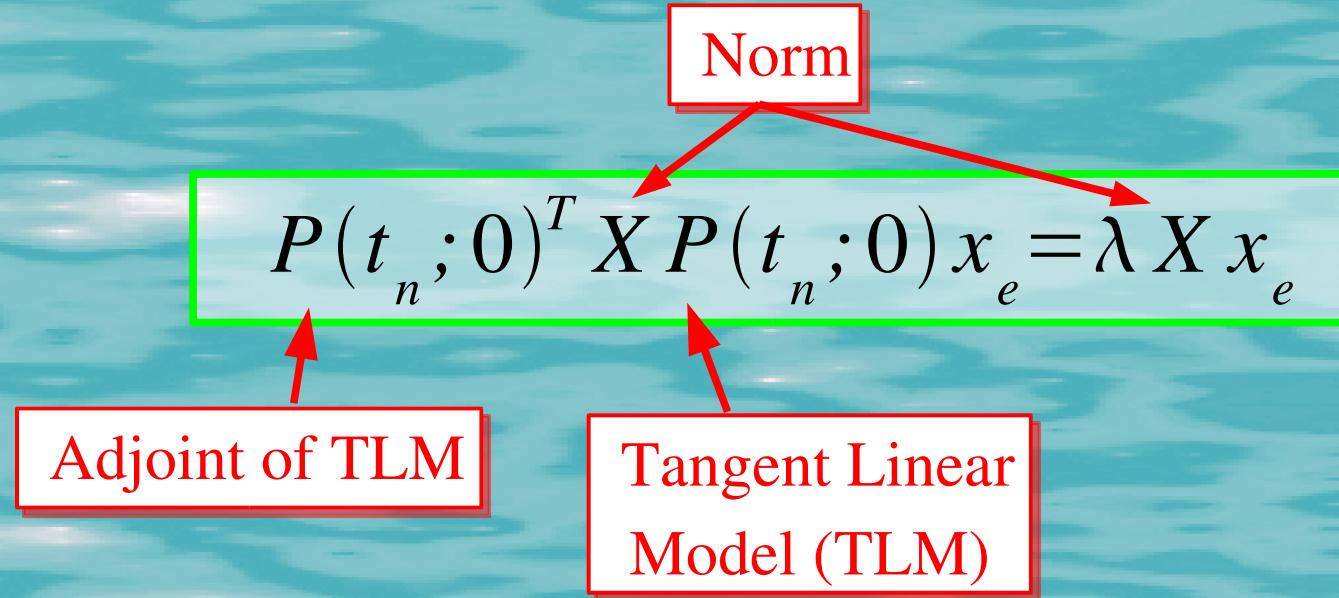
$$M \frac{d x'}{dt} = A x'$$

$$x = \bar{x} + x'$$

$$x'(t_{n+1}) = x'(t_n) P(t_{n+1}; t_n)$$

$$P(t_{n+1}; t_n) = [M - \theta \Delta t A]^{-1} [M + (1 - \theta) \Delta t A]$$

Generalized Stability Analysis



Generalized Stability Analysis

$$P(t_n; 0)^T X P(t_n; 0) x_e = \lambda X x_e$$



$$A x = \sigma B x$$

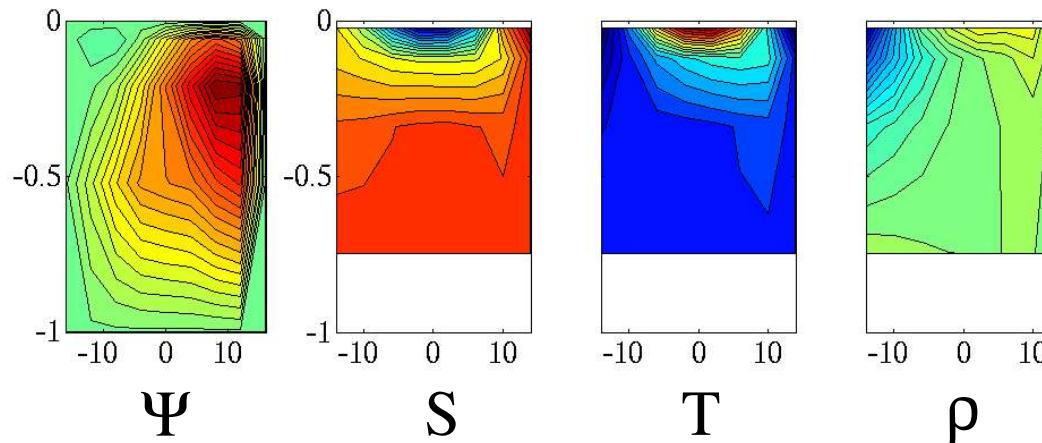
Generalized eigenproblem

Generalized Stability Analysis

Proof of concept

- Model THCM
 - Domain: 4x8x4

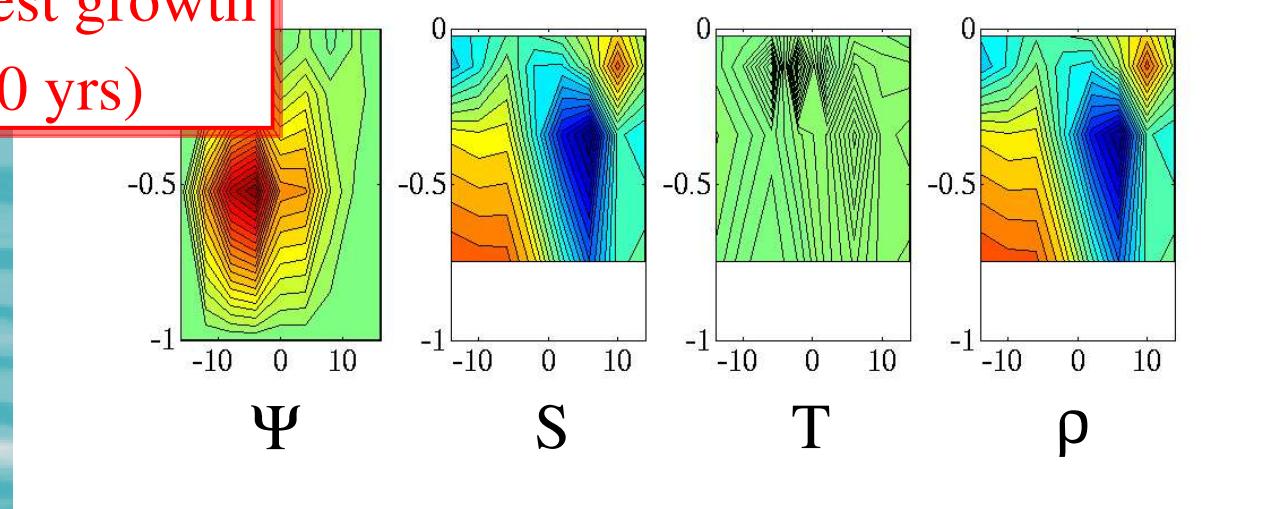
Basic State



Generalized Stability Analysis

Proof of concept

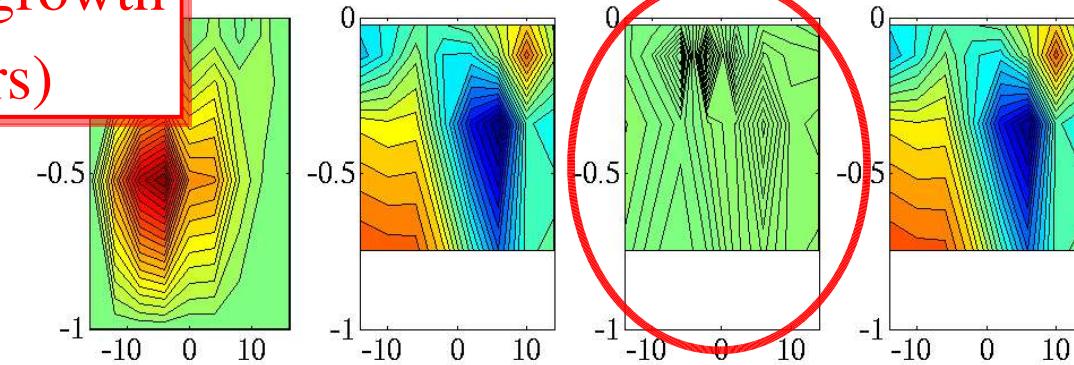
Initial perturbation
with strongest growth
(after 10 yrs)



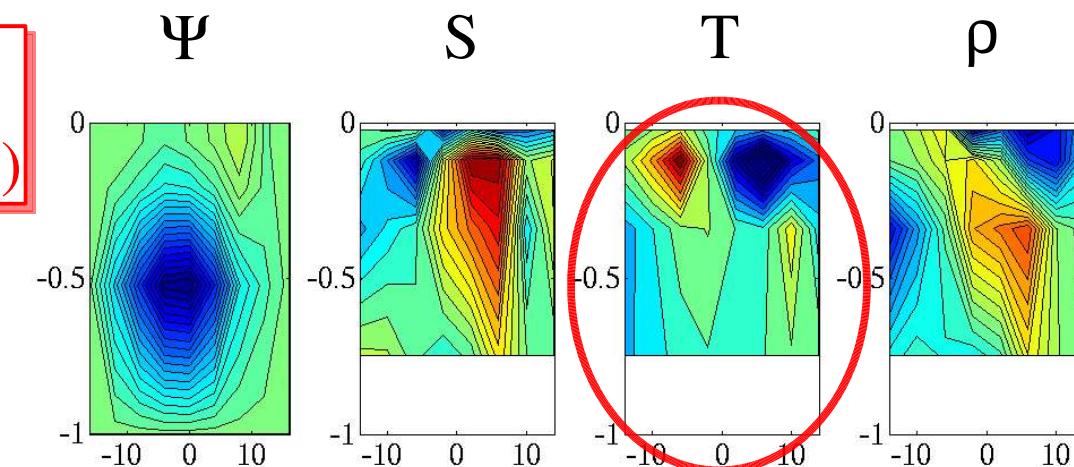
Generalized Stability Analysis

Proof of concept

Initial perturbation
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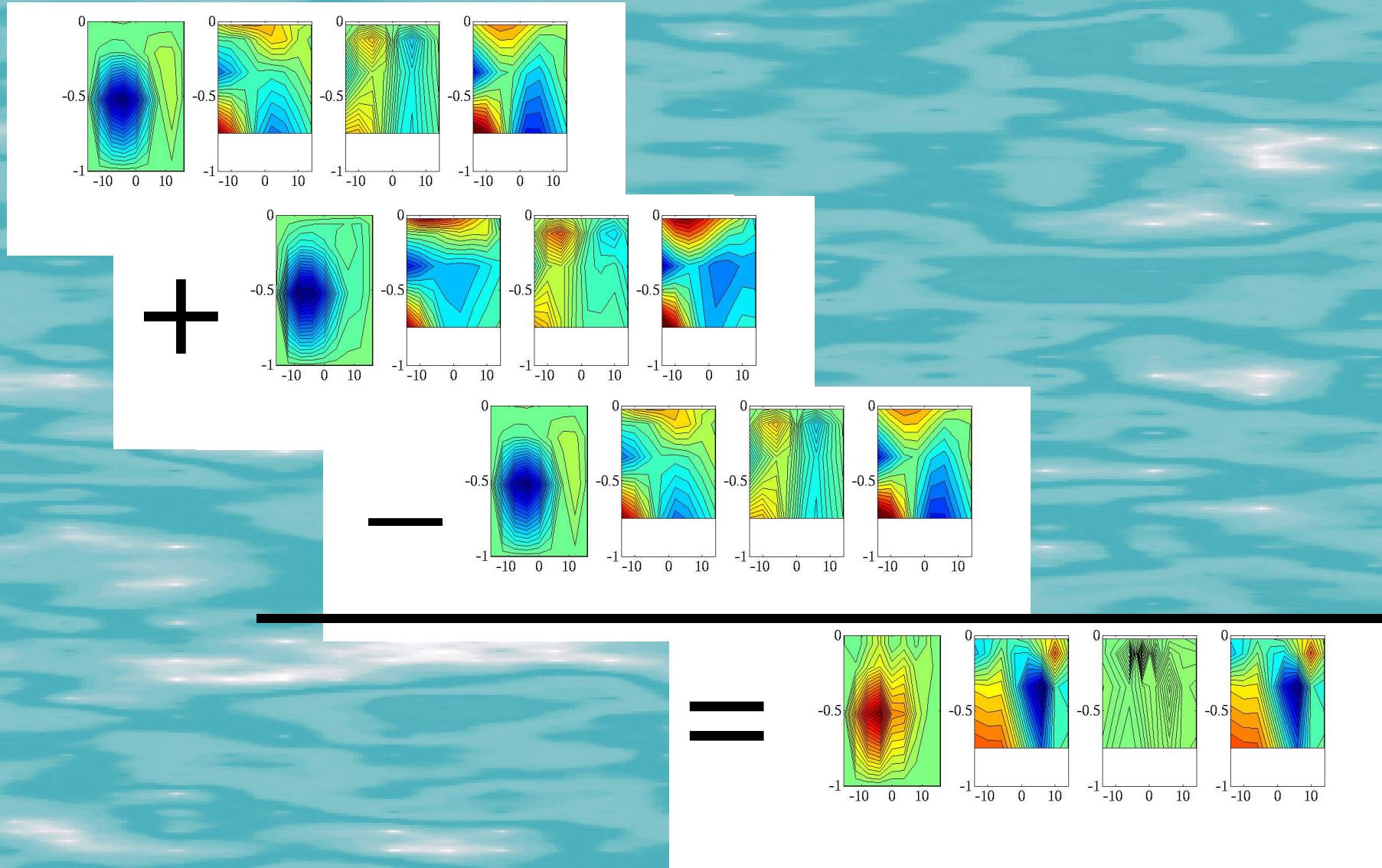


Final state
(after 10 yrs)



Generalized Stability Analysis

Proof of concept



Conclusions

- ➊ Implicit methods powerful tools to study ocean dynamics
 - Efficient time-stepping
 - Parameter continuation
 - Stability analysis: Linear & Generalized
- ➋ Current focus:
 - More efficient solvers
 - Improved ocean physics