

Energy, Geostrophic Adjustment, and a Momentum Analog to the Z-grid

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The Basic Questions

Can we conserve fundamental quantities such as potential enstrophy and total energy on the hexagonal grid?

What does the momentum formulation look like?
(ZM-grid staggering)

What does the vorticity-divergence formulation look like?
(Z-grid staggering)

How well is the process of geostrophic adjustment simulated on the hexagonal grid?

The ZM-grid staggering

All scalars at grid cell centers

Mass

Kinetic Energy

Vorticity

Divergence

All vectors at grid cell corners

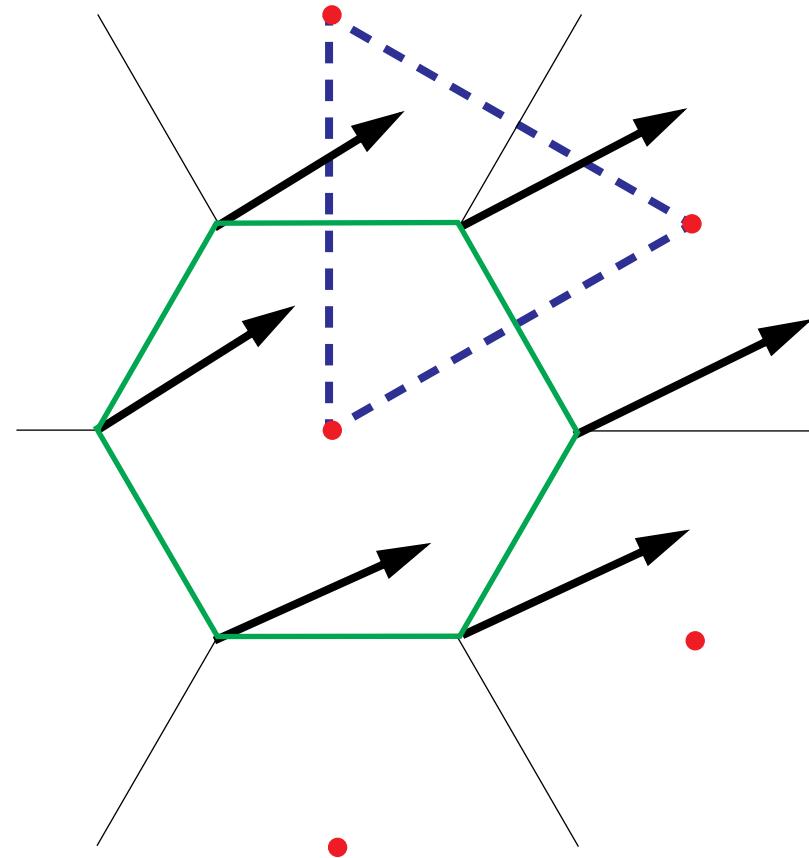
Velocity

Gradients of scalar fields

area of each momentum point

is $\frac{1}{2}$

the area of each mass point



The Shallow Water Equations

Continuous Equations

$$\frac{\partial h}{\partial t} = -\nabla \cdot (h \tilde{V})$$

$$\frac{\partial}{\partial t} \tilde{V} = -\eta \tilde{k} \times \tilde{V} - \nabla [K + gh]$$

Discrete Equations

$$\frac{\partial h_0}{\partial t} = -D_0[\bar{h}_c V_c]$$

$$\frac{\partial \tilde{V}_c}{\partial t} = -\bar{\eta}_c \tilde{k} \times \tilde{V}_c - G_c[K_0 + g h_0]$$

D_0 = discrete divergence operator

G_c = discrete gradient operator

\bar{h}_c = averaging of mass to cell corners

$\bar{\eta}_c$ = averaging of vorticity to cell corners

C_0 = discrete curl operator

Discrete Divergence and Curl Operators

Definition

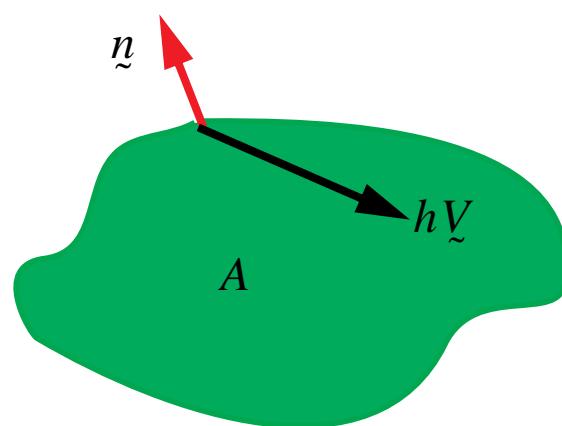
$$\nabla \bullet (h\tilde{V}) \equiv \lim_{A \rightarrow 0} \frac{1}{A} \int \tilde{n} \bullet h\tilde{V} \, dl$$

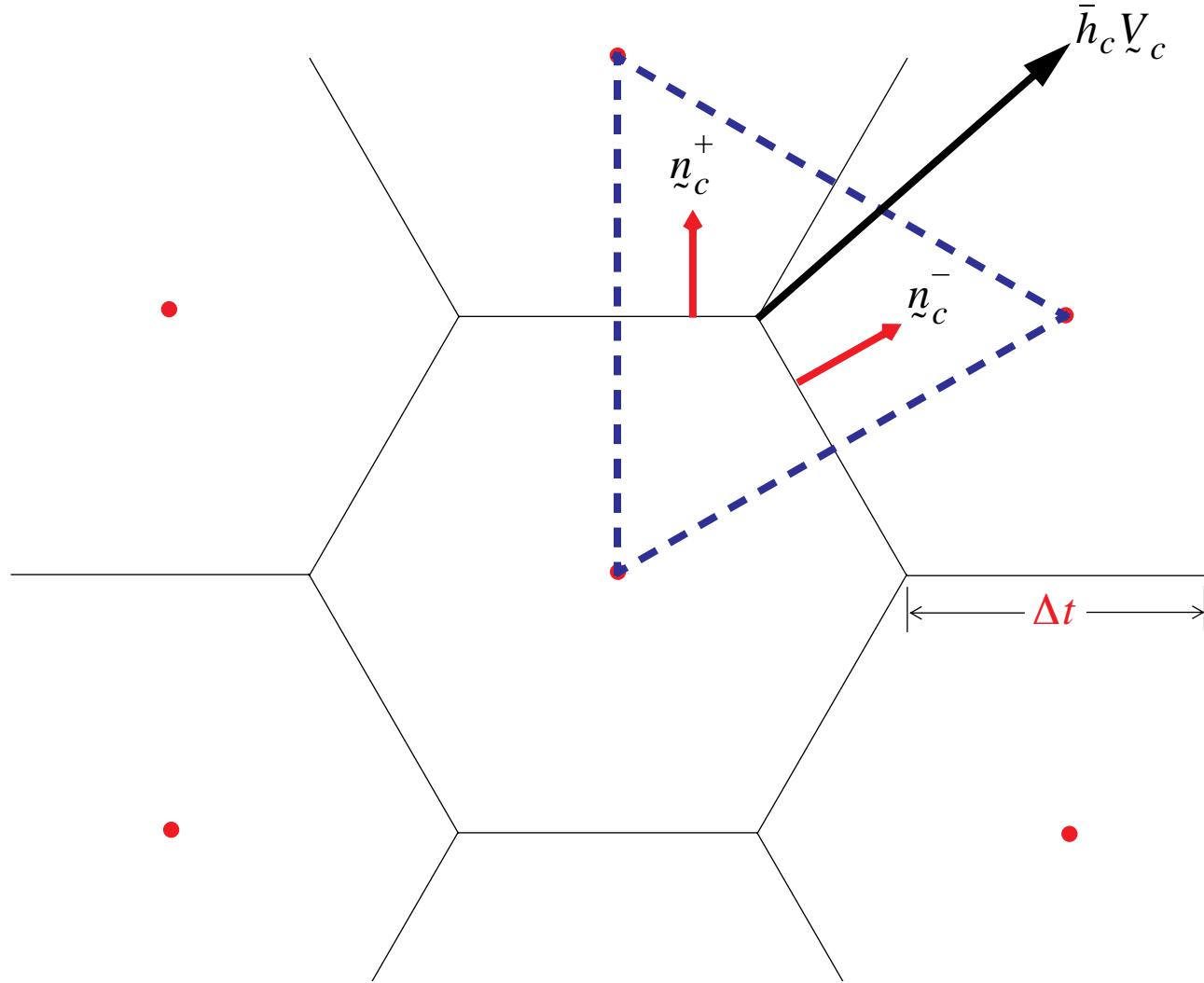
$$\nabla \times (h\tilde{V}) \equiv \lim_{A \rightarrow 0} \frac{1}{A} \int \tilde{n} \times h\tilde{V} \, dl$$

By Analogy

$$D_0(h\tilde{V}) = \frac{1}{A_0} \sum_{c=1}^6 (\tilde{n}_c^+ + \tilde{n}_c^-) \bullet \bar{h}_c V_c \left(\frac{\Delta t}{2} \right)$$

$$C_0(h\tilde{V}) = \frac{1}{A_0} \sum_{c=1}^6 (\tilde{n}_c^+ + \tilde{n}_c^-) \times \bar{h}_c V_c \left(\frac{\Delta t}{2} \right)$$





Conservation of Total Energy

Continuous Equations

$$K \left\{ \frac{\partial h}{\partial t} = -\nabla \cdot (h \tilde{V}) \right\}$$

$$gh \left\{ \frac{\partial h}{\partial t} = -\nabla \cdot (h \tilde{V}) \right\}$$

$$h \tilde{V} \cdot \left\{ \frac{\partial}{\partial t} V = -\eta \tilde{k} \times \tilde{V} - \nabla [K + gh] \right\}$$

$$\int_A h \left[K + \frac{1}{2} gh \right] dA = 0$$

Discrete Equations

$$K_0 \left\{ \frac{\partial h_0}{\partial t} = -D_0[\bar{h}_c, \tilde{V}_c] \right\}$$

$$gh_0 \left\{ \frac{\partial h_0}{\partial t} = -D_0[\bar{h}_c, \tilde{V}_c] \right\}$$

$$h_0 \sum_{c=1}^6 \tilde{V}_c \cdot \left\{ \frac{\partial \tilde{V}_c}{\partial t} = -\bar{\eta}_c \tilde{k} \times \tilde{V}_c - G_c[K_0 + gh_0] \right\}$$

$$\sum_{i=0}^n h_i \left[K_i + \frac{1}{2} g h_i \right] A_i = 0$$



We use our degrees of freedom in G_c , K_0 , and \bar{h}_c to make this happen.

So what are the forms of \tilde{G}_c , K_0 , and \bar{h}_c

The Gradient Operator

$$\tilde{G}_c(K) \bullet \varepsilon_1 = \frac{\Delta n}{A_c} \left[\left(\frac{K_1 + K_2}{2} \right) - K_0 \right]$$

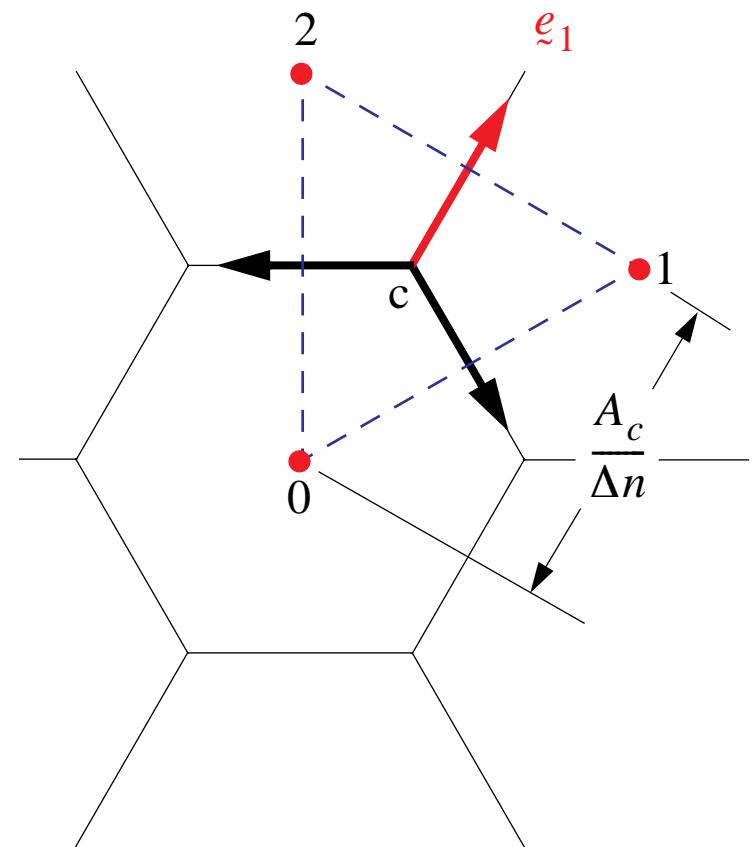
other components look similar

Kinetic Energy

$$K_0 = \frac{1}{6} \sum_{c=1}^6 \frac{1}{2} (\mathbf{V}_c \bullet \mathbf{V}_c)$$

The Mass Averaging Operator

$$\bar{h}_c = \frac{1}{3}(h_0 + h_1 + h_2)$$



A 2-D turbulence simulation

Momentum formulation of full shallow-water equations with free surface

doubly-periodic f-plane, $f = 1.0 \times 10^{-4} s^{-1}$

Initial Conditions: $h = 400 \pm 50m$, $\delta = \pm 5.0 \times 10^{-5} s^{-1}$, $\zeta = \pm 5.0 \times 10^{-5} s^{-1}$

Resolution: 128x128 grid, $\Delta n = 100km$, $\lambda = 700km$

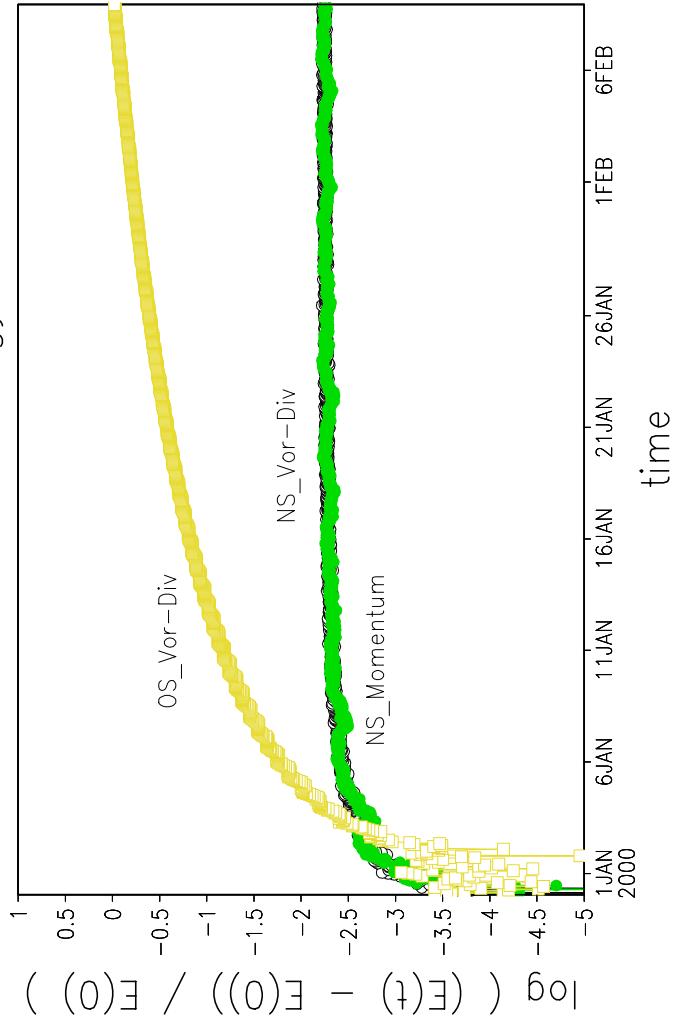
Simulation 1

Purpose: address conservation
integration length 40 days
no dissipation

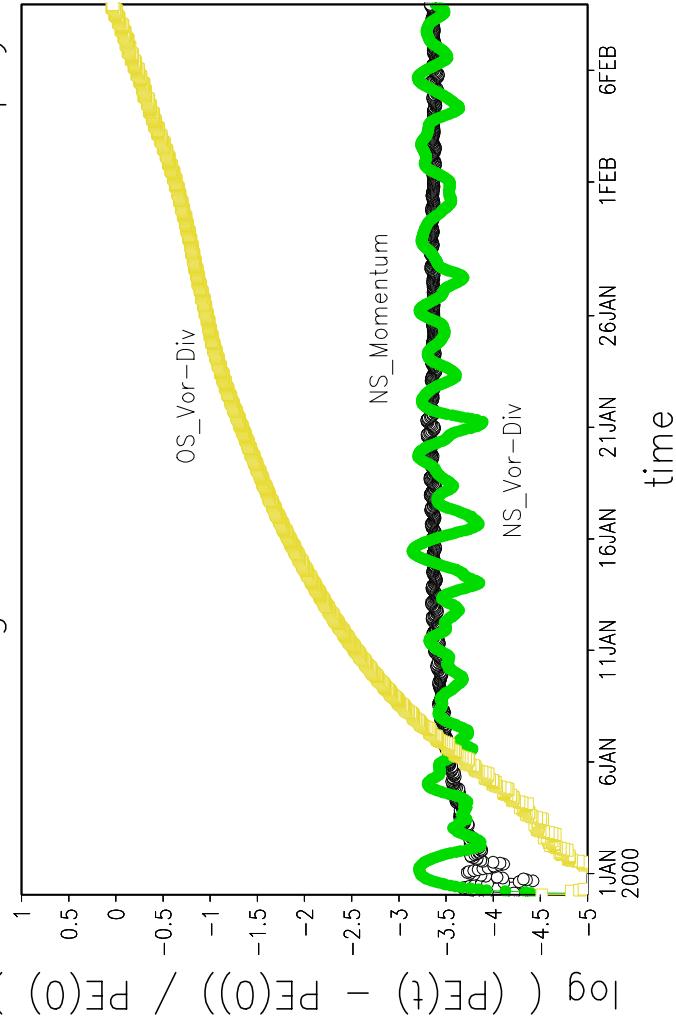
Simulation 2

Purpose: Energy and Enstrophy Cascade
integration length 2000 days
 ∇^6 diffusion on velocity vector

Total Energy



Mass-Weighted Potential Enstrophy



Exchanging the Momentum Formulation for the Vorticity-Divergence Formulation

Continuous Equations

$$\nabla \cdot \left\{ \frac{\partial}{\partial t} \tilde{V} = -\eta \tilde{k} \times \tilde{V} - \nabla [K + gh] \right\}$$

$$\nabla \times \left\{ \frac{\partial}{\partial t} \tilde{V} = -\eta \tilde{k} \times \tilde{V} - \nabla [K + gh] \right\}$$



$$\frac{\partial \delta}{\partial t} = \tilde{k} \cdot \nabla \times (\eta \tilde{V}) - \nabla^2 [K + gh]$$

$$\frac{\partial \eta}{\partial t} = -\nabla \cdot (\eta \tilde{V})$$

Discrete Equations

$$D_0 \left\{ \frac{\partial \tilde{V}_c}{\partial t} = -\bar{\eta}_c \tilde{k} \times \tilde{V}_c - \tilde{G}_c [K_0 + gh_0] \right\}$$

$$C_0 \left\{ \frac{\partial \tilde{V}_c}{\partial t} = -\bar{\eta}_c \tilde{k} \times \tilde{V}_c - \tilde{G}_c [K_0 + gh_0] \right\}$$

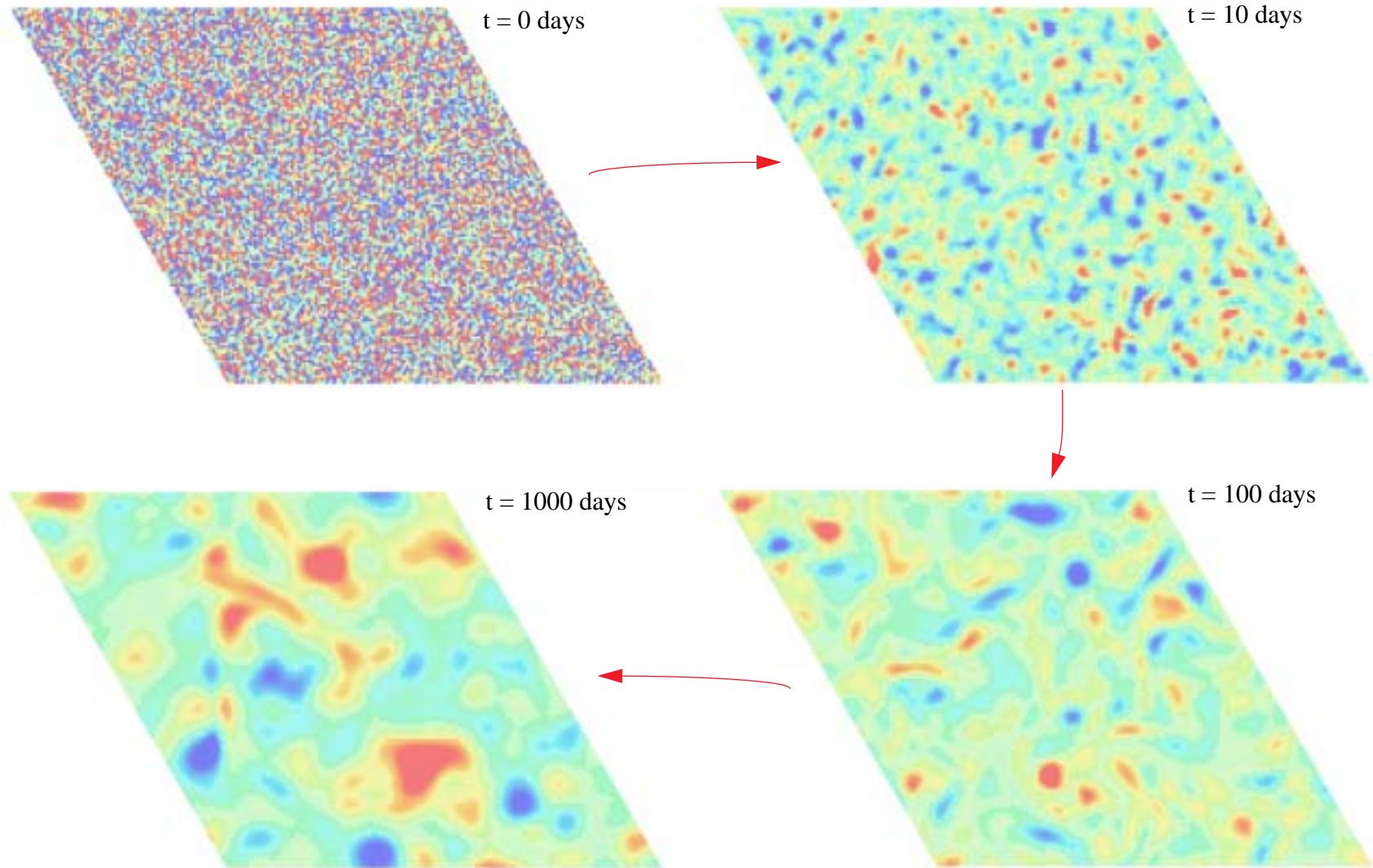


$$\frac{\partial \delta_0}{\partial t} = C_0(\eta \tilde{V}) - L_0[K + gh]$$

$$\frac{\partial \eta_0}{\partial t} = -D_0(\eta \tilde{V})$$

What does the discrete Laplacian look like?

Evolution of the vorticity field



So the nonlinear aspects, namely advection, checkout.

What about the linear system?

Why look at the linearized equations?

- 1) simulation of physical modes related to geostrophic adjustment
- 2) isotropy
- 3) check for the existence of computational modes

Momentum Formulation

$$\frac{\partial h_0}{\partial t} + H(\nabla \cdot \tilde{V})_0 = 0$$

$$\frac{\partial \tilde{V}_c}{\partial t} + fk \times \tilde{V}_c + g(\nabla h)_c = 0$$

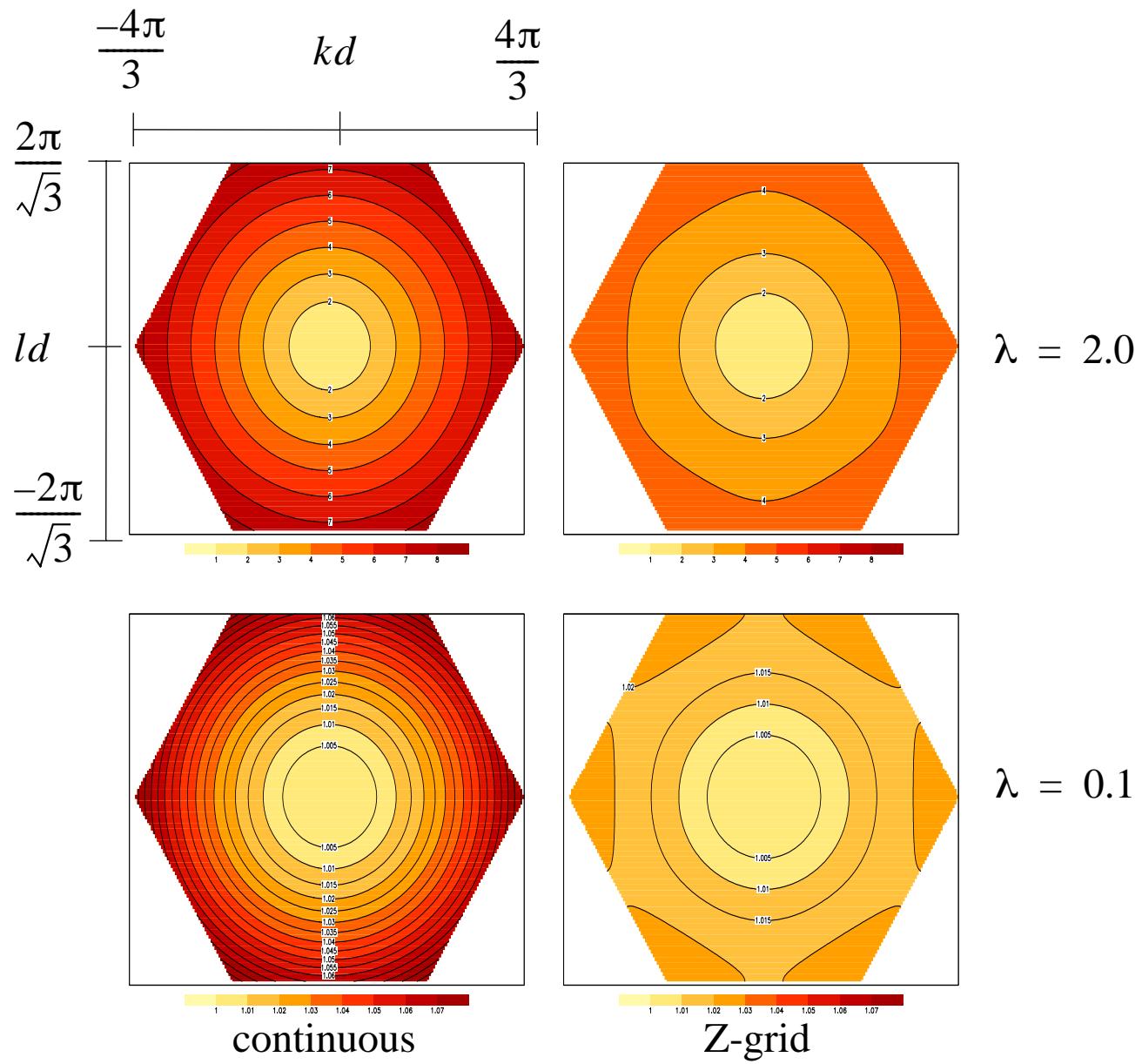
Vorticity-Divergence Formulation

$$\frac{\partial h_0}{\partial t} + H\delta_0 = 0$$

$$\frac{\partial \delta_0}{\partial t} - f\zeta_0 + g(\nabla^2 h)_0 = 0$$

$$\frac{\partial \zeta_0}{\partial t} + f\delta_0 = 0$$

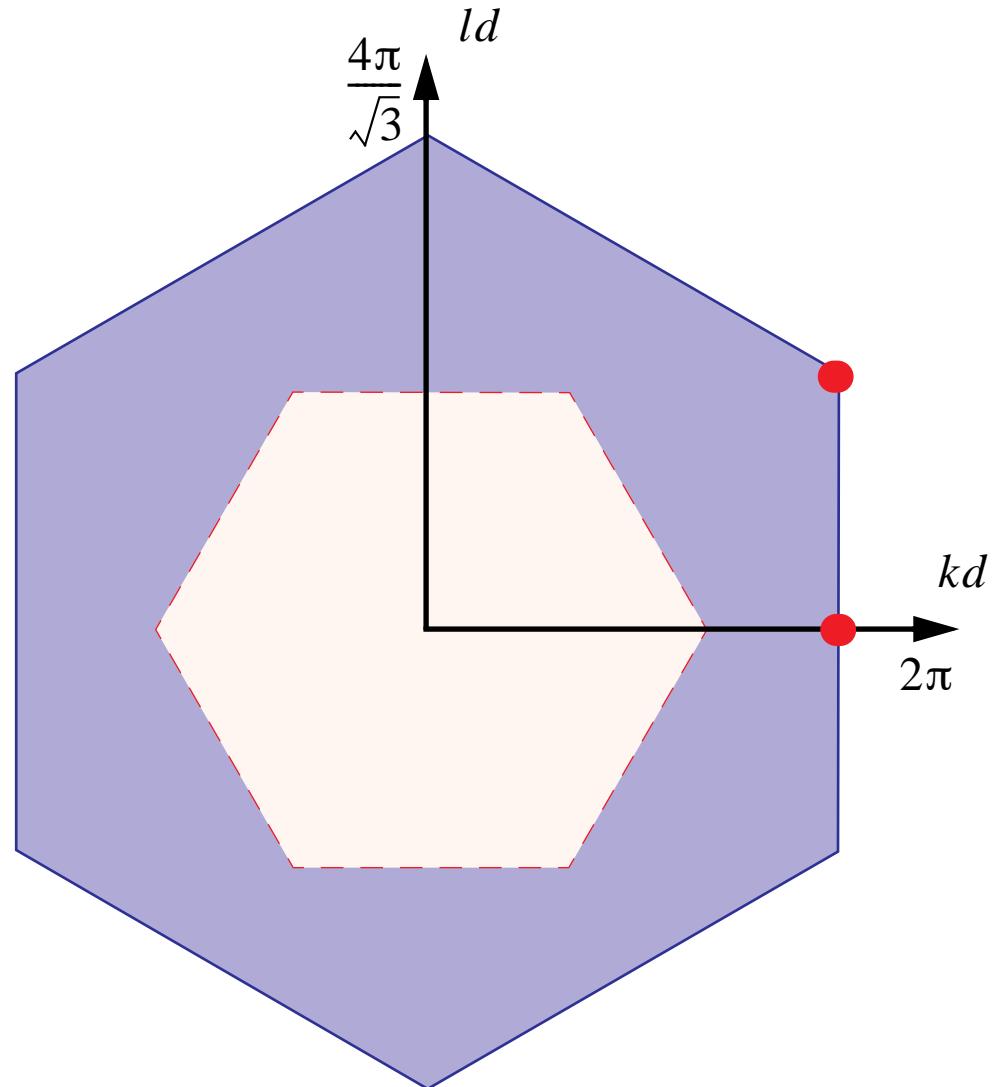
The three modes found in the Vorticity-Divergence formulation
are modes in the Momentum formulation.



Computational modes in the ZM-grid system

Mode Facts

- 1) no modes in height field
- 2) two modes in velocity field
- 3) modes exist at wave numbers not resolved by the scalar data.
- 4) a 2000 day 2-D turbulence simulation required no filtering
- 5) we have the perfect filter



Conclusions for the vorticity-divergence (Z-grid) formulation

- 1) New formulation conserves potential enstrophy and total energy.
- 2) The isotropy of the hexagonal grid is apparent in the simulation of the geostrophic adjustment process.
- 3) No computational modes



Conclusions for the momentum (ZM-grid) formulation

- 1) New formulation conserves potential enstrophy and total energy.
- 2) The isotropy of the hexagonal grid is apparent in the simulation of the geostrophic adjustment process.
- 3) Two benign* computational modes in the velocity equation

*at least so far



Where to from here?

- 1) generalize to the sphere
- 2) test in dynamical core (predict vorticity-divergence and momentum interchangeably)
- 3) build an ocean model

<http://kiwi.atmos.colostate.edu/BUGS/projects/geodesic>

What is there?

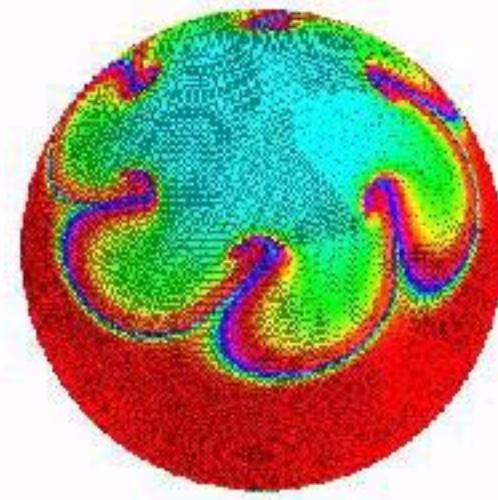
shallow water model source code

domain decomposition (MPI)

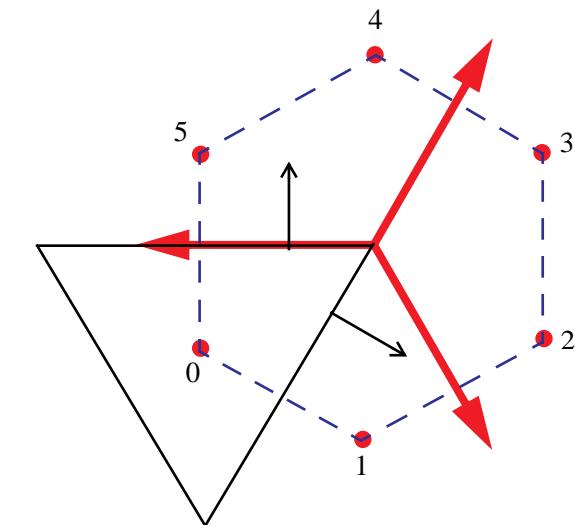
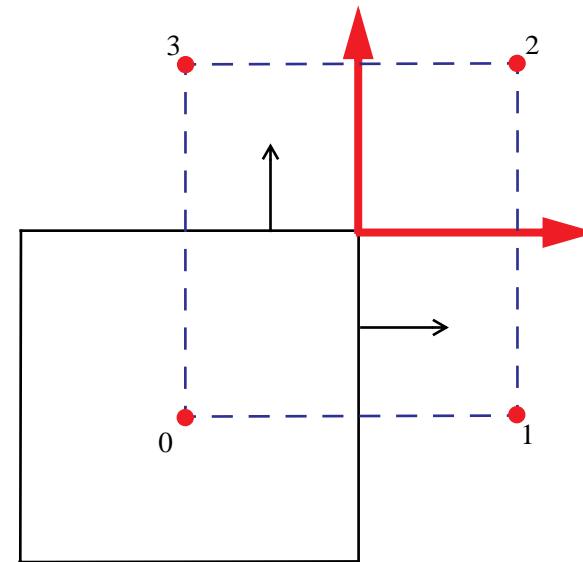
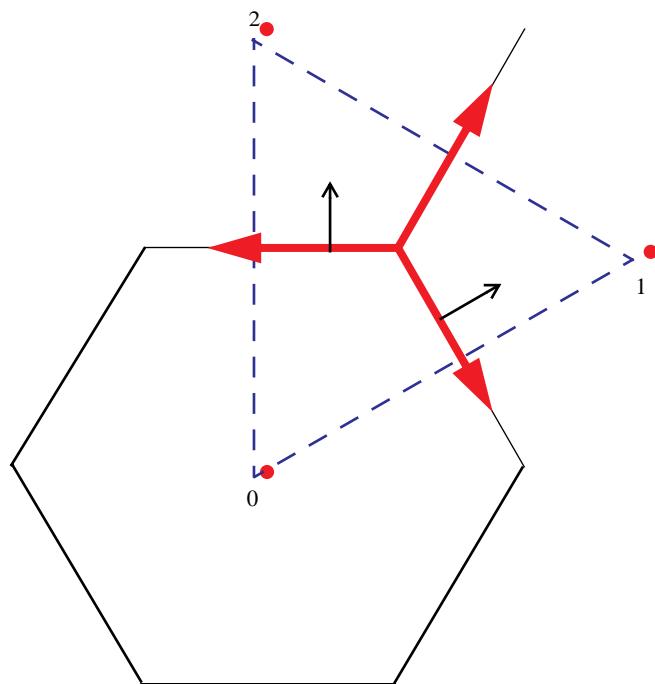
conservative remapping (SCRIP)

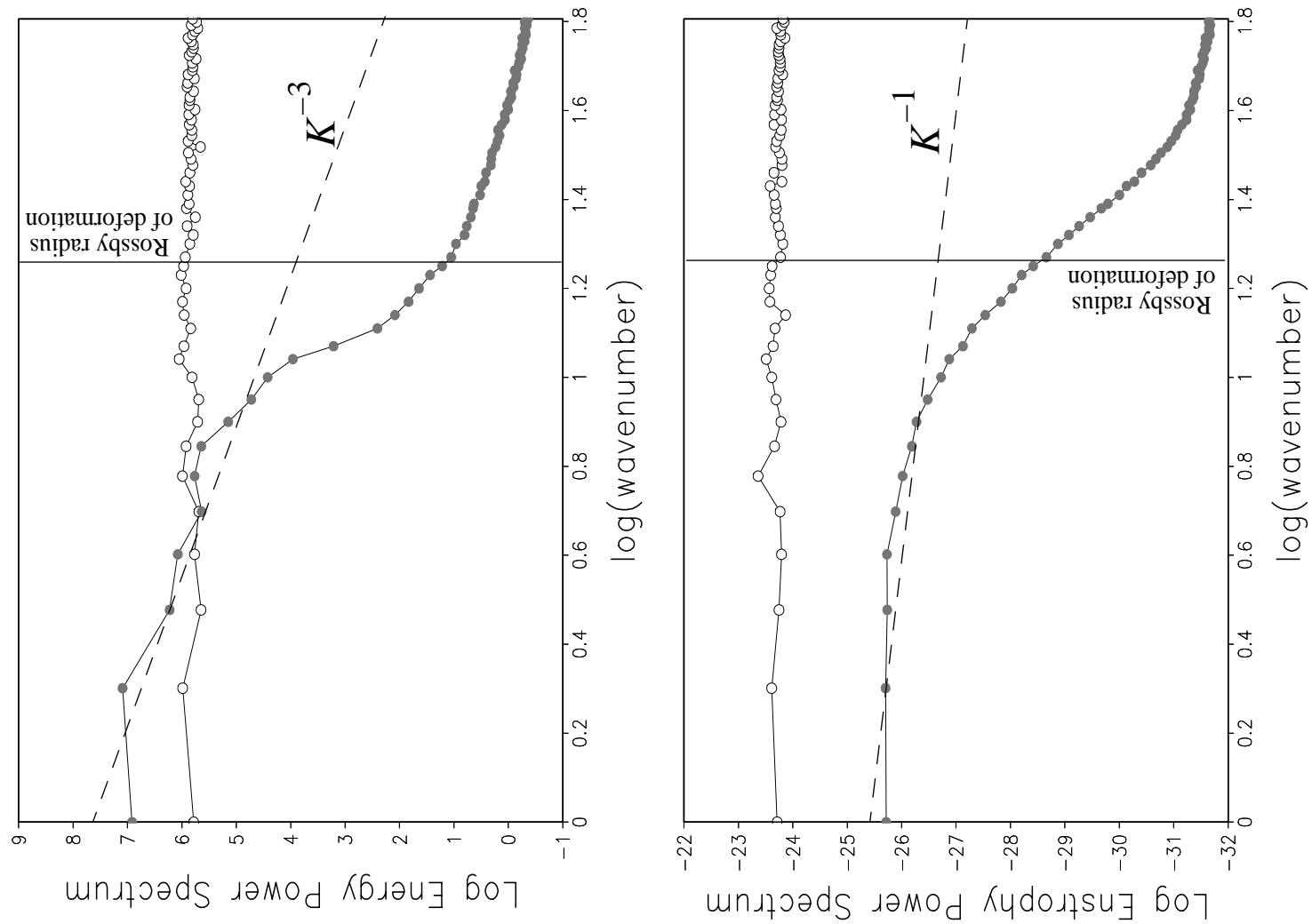
technical papers

slide show (intro to geodesic grids)

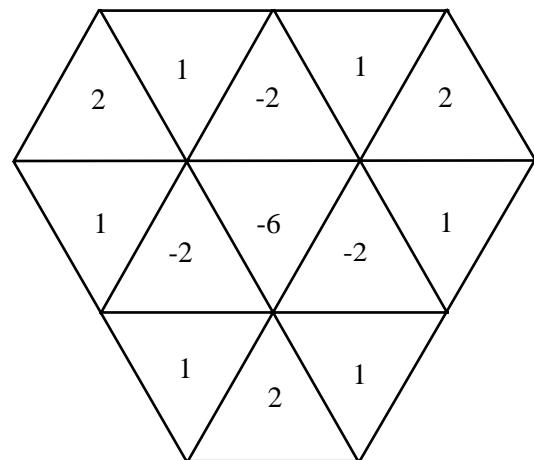
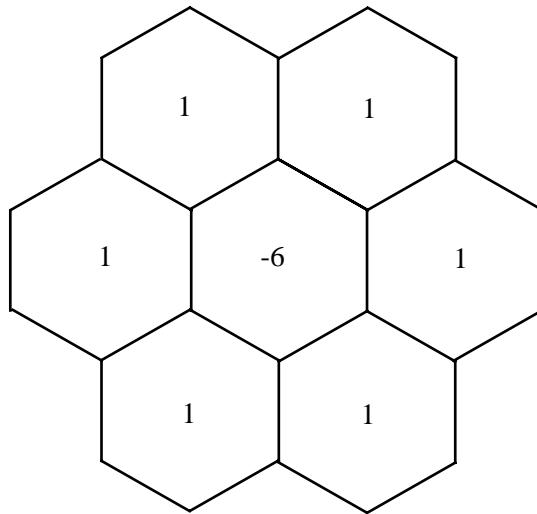


ZM-grid staggering in other geometries

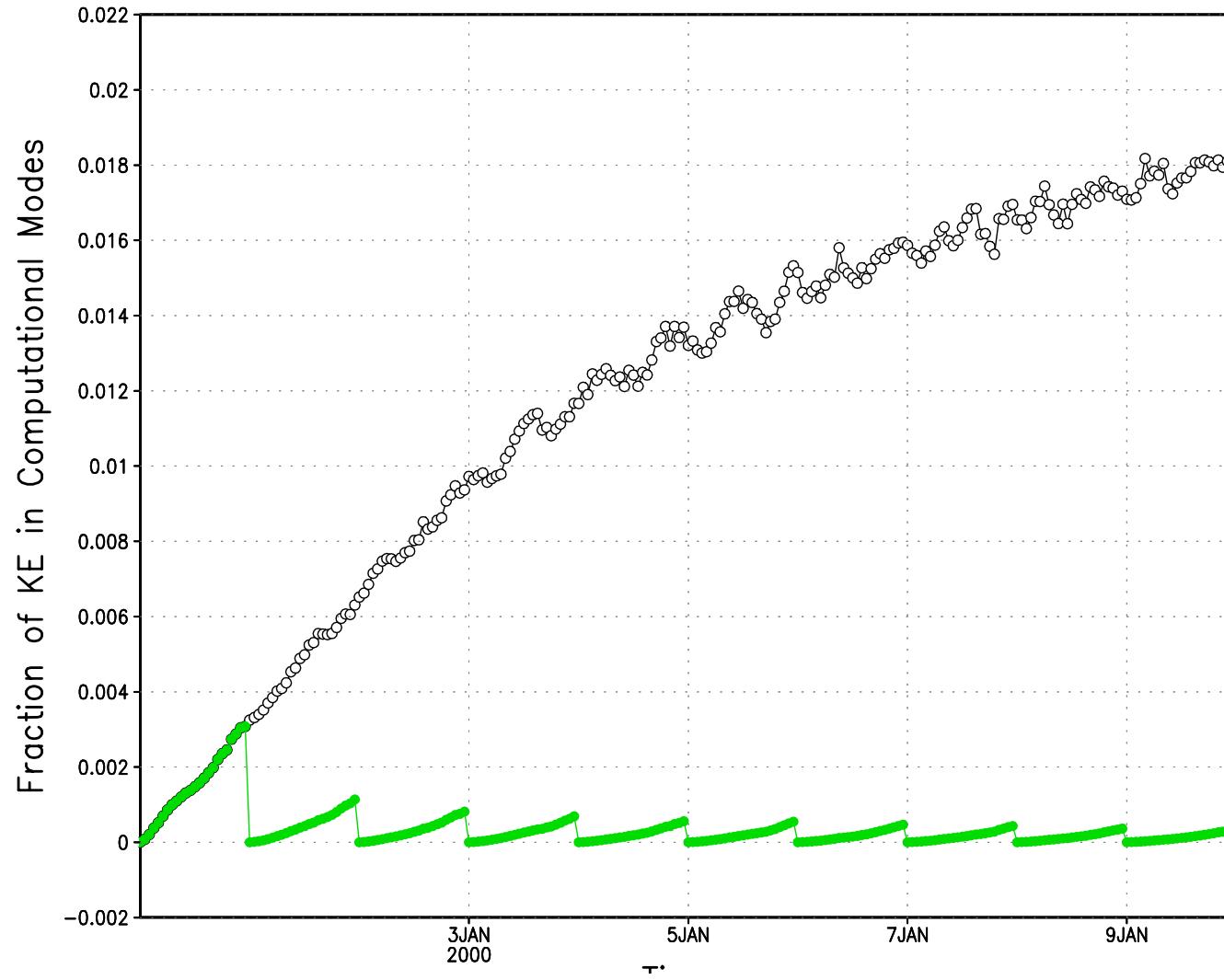




What does the energy-conserving Laplacian look like?



1		1
	-4	
1		1



The discrete Laplacian is identical to one we are currently using.

